

# Thyristor Modules

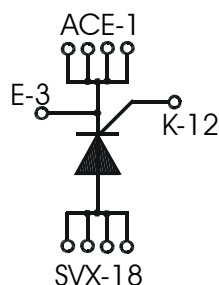
## ECO-PAC 2

$$I_{TRMS} = 280 \text{ A}$$

$$I_{TAVM} = 180 \text{ A}$$

$$V_{RRM} = 1200/1600 \text{ V}$$

| $V_{RSM}$      | $V_{RRM}$      | Typ             |
|----------------|----------------|-----------------|
| $V_{DSM}$<br>V | $V_{DRM}$<br>V |                 |
| 1300           | 1200           | VCO 180 - 12io7 |
| 1700           | 1600           | VCO 180 - 16io7 |



| Symbol         | Conditions                                                                                                                       | Maximum Ratings |                  |
|----------------|----------------------------------------------------------------------------------------------------------------------------------|-----------------|------------------|
| $I_{TRMS}$     |                                                                                                                                  | 280             | A                |
| $I_{TAVM}$     | $T_C = 90^\circ\text{C}; T_{VJ} = 130^\circ\text{C}; 180^\circ \text{ sine}$                                                     | 180             | A                |
| $I_{TSM}$      | $T_{VJ} = 45^\circ\text{C}; t = 10 \text{ ms} \quad (50 \text{ Hz})$                                                             | 4500            | A                |
|                | $V_R = 0 \quad t = 8.3 \text{ ms} \quad (60 \text{ Hz})$                                                                         | 4900            | A                |
|                | $T_{VJ} = 125^\circ\text{C}; t = 10 \text{ ms} \quad (50 \text{ Hz})$                                                            | 3800            | A                |
|                | $V_R = 0 \quad t = 8.3 \text{ ms} \quad (60 \text{ Hz})$                                                                         | 4200            | A                |
| $I^2t$         | $T_{VJ} = 45^\circ\text{C}; t = 10 \text{ ms} \quad (50 \text{ Hz})$                                                             | 101 000         | A <sup>2</sup> s |
|                | $V_R = 0 \quad t = 8.3 \text{ ms} \quad (60 \text{ Hz})$                                                                         | 99 500          | A <sup>2</sup> s |
|                | $T_{VJ} = 125^\circ\text{C}; t = 10 \text{ ms} \quad (50 \text{ Hz})$                                                            | 72 000          | A <sup>2</sup> s |
|                | $V_R = 0 \quad t = 8.3 \text{ ms} \quad (60 \text{ Hz})$                                                                         | 73 000          | A <sup>2</sup> s |
| $(di/dt)_{cr}$ | $T_{VJ} = 125^\circ\text{C};$ repetitive, $I_T = 250 \text{ A}$<br>$f = 50 \text{ Hz}; t_p = 200 \mu\text{s};$                   | 150             | A/ $\mu\text{s}$ |
|                | $V_D = \frac{2}{3} V_{DRM};$ non repetitive, $I_T = I_{TAVM}$<br>$I_G = 0.5 \text{ A};$<br>$di_G/dt = 0.5 \text{ A}/\mu\text{s}$ | 500             | A/ $\mu\text{s}$ |
| $(dv/dt)_{cr}$ | $T_{VJ} = 125^\circ\text{C}; V_D = \frac{2}{3} V_{DRM};$<br>$R_{GK} = \infty;$ method 1 (linear voltage rise)                    | 1000            | V/ $\mu\text{s}$ |
| $P_{GM}$       | $T_{VJ} = 125^\circ\text{C}; t_p = 30 \text{ ms}$                                                                                | $\leq 10$       | W                |
| $P_{GAVM}$     | $I_T = I_{T(AV)M}; t_p = 300 \text{ ms}$                                                                                         | $\leq 5$        | W                |
|                |                                                                                                                                  | 0.5             | W                |
| $V_{RGM}$      |                                                                                                                                  | 10              | V                |
| $T_{VJ}$       |                                                                                                                                  | -40...+130      | °C               |
| $T_{VJM}$      |                                                                                                                                  | 150             | °C               |
| $T_{stg}$      |                                                                                                                                  | -40...+125      | °C               |
| $V_{ISOL}$     | 50/60 Hz, RMS $t = 1 \text{ min}$                                                                                                | 3000            | V~               |
|                | $I_{ISOL} \leq 1 \text{ mA} \quad t = 1 \text{ s}$                                                                               | 3600            | V~               |
| $M_d$          | Mounting torque (M4)                                                                                                             | 1.5 - 2.0       | Nm               |
|                |                                                                                                                                  | 14 - 18         | lb.in.           |
| Weight         | Typical including screws                                                                                                         | 24              | g                |

### Features

- Isolation voltage 3600 V~
- Planar glass passivated chips
- Low forward voltage drop
- Leads suitable for PC board soldering

### Applications

- DC Motor control
- Light and temperature control
- Softstart AC motor controller
- Solid state switches

### Advantages

- Easy to mount with two screws
- Space and weight savings
- Improved temperature and power cycling
- High power density
- Small and light weight

Data according to IEC 60747 and refer to a single diode unless otherwise stated.

IXYS reserves the right to change limits, test conditions and dimensions.

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| Symbol     | Conditions                                                                                                                    | Characteristic Values |                |
|------------|-------------------------------------------------------------------------------------------------------------------------------|-----------------------|----------------|
|            |                                                                                                                               | typ.                  | max.           |
| $I_D, I_R$ | $V_R / V_D = V_{RRM} / V_{DRM}$<br>$T_{VJ} = 125^\circ\text{C}$                                                               | 10                    | mA             |
| $V_T$      | $I_T = 200\text{ A}$<br>$T_{VJ} = 25^\circ\text{C}$                                                                           | 1.1                   | V              |
| $V_{T0}$   | For power-loss calculations only                                                                                              | 0.75                  | V              |
| $r_t$      |                                                                                                                               | 1.23                  | mΩ             |
| $V_{GT}$   | $V_D = 6\text{ V}$<br>$T_{VJ} = 25^\circ\text{C}$                                                                             | 1.5                   | V              |
| $I_{GT}$   | $V_D = 6\text{ V}$<br>$T_{VJ} = -40^\circ\text{C}$<br>$T_{VJ} = 25^\circ\text{C}$<br>$T_{VJ} = -40^\circ\text{C}$             | 1.6<br>300<br>400     | V<br>mA<br>mA  |
| $V_{GD}$   | $V_D = \frac{2}{3} V_{DRM}$<br>$T_{VJ} = 125^\circ\text{C}$                                                                   | 0.2                   | V              |
| $I_{GD}$   |                                                                                                                               | 10                    | mA             |
| $I_L$      | $t_p = 10\text{ }\mu\text{s}$ ;<br>$I_G = 0.5\text{ A}$ ; $di_G/dt = 0.5\text{ A}/\mu\text{s}$<br>$T_{VJ} = 25^\circ\text{C}$ | 450                   | mA             |
| $I_H$      | $V_D = 6\text{ V}$ ; $R_{GK} = \infty$ ;<br>$T_{VJ} = 25^\circ\text{C}$                                                       | 200                   | mA             |
| $t_{gd}$   | $V_D = \frac{1}{2} V_{DRM}$<br>$I_G = 0.5\text{ A}$ ; $di_G/dt = 0.5\text{ A}/\mu\text{s}$<br>$T_{VJ} = 25^\circ\text{C}$     | 2                     | $\mu\text{s}$  |
| $R_{thJC}$ | per thyristor; DC current                                                                                                     | 0.17                  | K/W            |
| $R_{thJH}$ |                                                                                                                               | 0.23                  | K/W            |
| $d_s$      | Creeping distance on surface                                                                                                  | 11.2                  | mm             |
| $d_A$      | Creepage distance in air                                                                                                      | 5.0                   | mm             |
| $a$        | Maximum allowable acceleration                                                                                                | 50                    | $\text{m/s}^2$ |

Dimensions in mm (1 mm = 0.0394")

