

MPS MODBUS TCP & ETHERNET/IP INTERFACE

REVISION 1-B-061115

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TABLE OF CONTENTS

| SECTION | PAGE |
|-------------------------------------------------------------------------------------|-----------|
| PART A: MODBUS TCP | |
| 1 General..... | 1 |
| 2 EtherNet Protocol | 1 |
| 2.1 Protocol Setup | 1 |
| 2.2 LED Indication..... | 1 |
| 2.3 Communication Status and Timeout..... | 1 |
| 2.4 File System..... | 2 |
| 3 Modbus TCP Protocol | 3 |
| 3.1 Function Codes Supported | 3 |
| 3.2 Register Database..... | 3 |
| 3.3 Reading Data Records..... | 3 |
| 3.4 User-Defined Registers | 3 |
| 3.5 Timeout Prevention..... | 4 |
| 3.6 Error Responses | 4 |
| 4 Specifications | 4 |
| PART B: ETHERNET/IP | |
| 1 General..... | 5 |
| 2 Ethernet Protocol | 5 |
| 2.1 Protocol Setup | 5 |
| 2.2 LED Indication..... | 5 |
| 2.3 Communication Status and Timeout..... | 5 |
| 2.4 File System..... | 5 |
| 3 EtherNet/IP | 7 |
| 3.1 EtherNet/IP Input Data Object Read..... | 7 |
| 3.2 EtherNet/IP Output Data Object Write | 7 |
| 3.3 Timeout Prevention..... | 8 |
| 3.4 Network Configuration Files..... | 8 |
| 3.5 RSLOGIX5000 Setup | 8 |
| 4 Classes | 9 |
| 4.1 Identity Object 0x01..... | 9 |
| 4.2 Control Supervisor 0x29 | 9 |
| 4.3 Overload Class 0x2C | 13 |
| 4.4 Set Point Class 0x64 | 15 |
| 4.5 Acceleration Class 0x65..... | 20 |
| 4.6 Digital Input Class 0x66 | 21 |
| 4.7 Analog I/O Class 0x67..... | 24 |
| 4.8 RTD Module Class 0x68..... | 25 |
| 4.9 RTC Class 0x69 | 31 |
| 4.10 User Register Class 0x6A | 32 |
| 4.11 Data Logging Class 0x6B | 33 |
| 5 Hardware Specifications..... | 35 |
| Appendix A MPS Modbus TCP & EtherNet/IP Interface Revision History | 36 |

LIST OF FIGURES

| FIGURE | PAGE |
|-----------------------------------------|------|
| PART A: MODBUS TCP | |
| 1 MPS-CTU Side View Showing LED's | 2 |
| PART B: ETHERNET/IP | |
| 2 MPS-CTU Side View Showing LED's | 6 |

LIST OF TABLES

| TABLE | PAGE |
|----------------------------------------------|------|
| PART A: MODBUS TCP | |
| 1 LED 2 – Module Status | 1 |
| 2 LED 3 – Network Status | 1 |
| 3 Supported Commands | 3 |
| PART B: ETHERNET/IP | |
| 4 LED 2 – Module Status | 5 |
| 5 LED 3 – Network Status | 5 |
| 6 MPS Command Table | 7 |
| 7 EtherNet/IP Control Command Assembly | 7 |

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PART A: MODBUS TCP

1. GENERAL

The Ethernet interface supports Modbus TCP and EtherNet/IP. For firmware revision 2.50 and higher a new version of Modbus TCP has been added in addition to the legacy version. This new version removes MPS register-access limitations and provides full access to all MPS parameters. The new version is compatible with SE-Comm-RIS. For legacy applications, the old functionality is still provided.

Starting with version 2.50, setting the IP address and mask is done using an OPI menu selection and does not require the “IPConfig” configuration software. This applies to both the Modbus TCP and EtherNet/IP versions.

This manual describes the features of the Modbus TCP version of EtherNet/IP. MPS firmware revision 2.5 or higher is required. For EtherNet/IP, see the MPS EtherNet/IP manual.

Section 2 is common for all Ethernet protocols and Section 3 describes the new Modbus TCP implementation.

2. ETHERNET PROTOCOL

This section applies to both legacy and new versions of Modbus TCP, and EtherNet/IP.

2.1 PROTOCOL SETUP

The protocol type, IP address, IP Mask, and default gateway are set in the *Setup / Hardware / Network Comms* menu.

For new installations requiring Modbus TCP, select *Modbus TCP*. This provides full access to the MPS parameters as described in the MPS manual Appendix E. Multiple-register read and write instructions are supported and write requests do not require a special command sequence. This selection is compatible with SE-Comm-RIS and is recommended for new installations. This mode of operation is described in Section 3.

Starting with MPS Version 2.50 IPConfig⁽¹⁾ is not required because the IP Address, Mask, and gateway are set using the *Ethernet IP* and *Ethernet Mask* menu settings, however, IPConfig can still be used to determine the IP Address, Mask, and gateway settings for connected devices.

2.2 LED INDICATION

The module contains four LED indicators as shown in Fig. 1.

LED 1 - Link

Indicates that the module is connected to an Ethernet network.

TABLE 1 LED 2 - MODULE STATUS

| STATE | DESCRIPTION |
|--------------------|--------------------|
| Steady Off | No Power |
| Steady Green | Device Operational |
| Flashing Green | Standby |
| Flashing Red | Minor Fault |
| Steady Red | Major Fault |
| Flashing Green/Red | Self-Test |

TABLE 2 LED 3 - NETWORK STATUS

| STATE | DESCRIPTION |
|--------------------|---------------------------|
| Steady Off | No Power or No IP Address |
| Steady Green | Connected |
| Flashing Green | No Connections |
| Flashing Red | Connection Timeout |
| Steady Red | Duplicate IP |
| Flashing Green/Red | Self-Test |

LED 4 - Activity LED

Flashes green each time a packet is received or transmitted.

2.3 COMMUNICATION STATUS AND TIMEOUT

The status of the Ethernet communication module is indicated as “Ethernet: ONLINE” when the module is operating properly, and as “Ethernet: OFFLINE” when the module is not operating properly. Module errors require the module to be reinitialized. The module is initialized on power up or can be initialized using the OPI. To initialize the module using the OPI, first disable the module by selecting *None* in the *Setup / Hardware / Network Type* menu and then select *Anybus* or *Modbus TCP* to enable the module.

In applications where the MPS start/stop functions are controlled by the network, the MPS can be configured to trip or alarm on loss of communication to the module. This feature is enabled using the *Setup / Hardware / Network Comms / Network Error* menu.

To prevent a timeout trip when using the *Modbus TCP* selection, see Section 3.5.

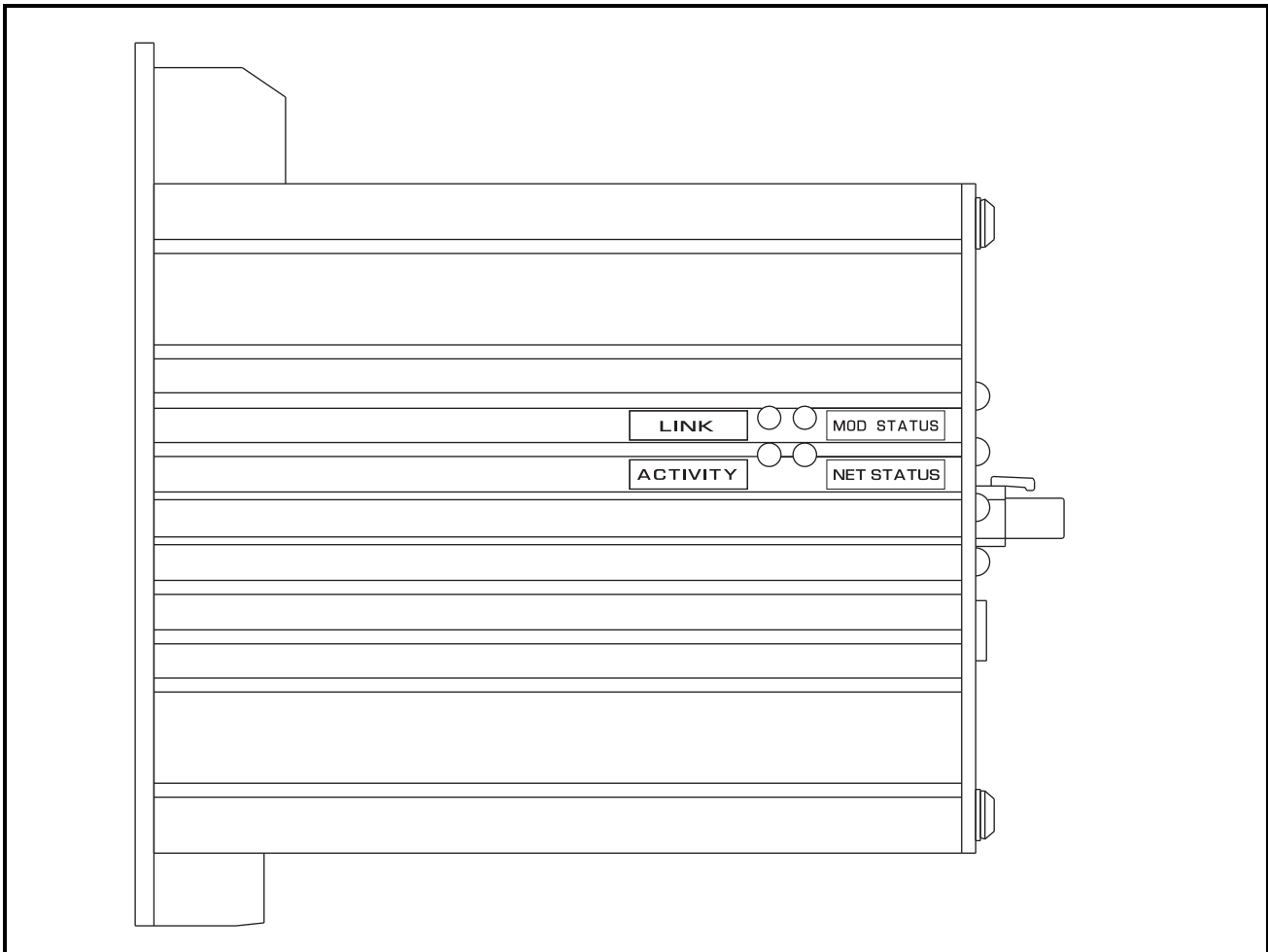


FIGURE 1. MPS-CTU Side View Showing LED's.

2.4 FILE SYSTEM

The module contains a file system that may be useful for storing files associated with the MPS. The file system is a fixed-size storage area with a hierarchical directory structure.

The file system is accessible via FTP, Telnet, HTTP.

The file system is case sensitive. This means that the file 'AnyBus.txt' is not identical to the file 'AnyBus.TXT'. Filenames can be a maximum of 48 characters long. Pathnames can be 256 characters in total, filename included.

NOTES:

- (1) Although IPConfig software can still be used to set the IP address, mask, and gateway these settings are temporary and overwritten by the menu-system value when the MPS Ethernet driver is re-started during powerup or when network parameters are changed.
- (2) The MPS communication address is defined by the *Ethernet IP* setting and is unique for each MPS. The

Network ID setting is ignored by the MPS. The Modbus broadcast address of 255 is not supported.

- (3) Communications options are mutually exclusive. Selecting *Anybus* or *Modbus TCP* disables the RS-485 interface.
- (4) Select *Anybus* or *Modbus TCP* only if the MPS has the Ethernet option installed (MPS-CTU-04-XX).

3. MODBUS TCP PROTOCOL

The MPS implements the Modbus TCP protocol on port 502. The MPS is a slave (server) on the network. It cannot initiate communication. Up to 5 clients can be connected simultaneously to a single MPS server.

3.1 FUNCTION CODES SUPPORTED

The MPS supports the following function codes:

- Read Holding Registers (Function Code 3)
- Read Input Registers (Function Code 4)
- Write Single Register (Function Code 6)
- Write Multiple Registers (Function Code 16)
- Force Single Coil (Function Code 5)

Function Code 3 and Function Code 4 perform the same function and are used to read data from the MPS. Function Code 6 and Function Code 16 are used to write data to the MPS. See MPS Manual Appendix E for the Modbus register list and address definitions. These functions use Modbus address group 4.

Function Code 5 is used to issue commands to the MPS. The command code and action is listed in Table 3. In terms of Modbus, the command code is the coil address (Modbus address group 0). The command is issued by setting the coil to ON at the specified address location. All commands use the ON request to issue the command. For example, to reset trips, the coil at Modbus coil address 00004 is set to ON. Coil commands are “one-shot” commands.

TABLE 3 SUPPORTED COMMANDS

| COMMAND CODE | COIL ADDRESS | ACTION |
|--------------|--------------|-------------------------------------------|
| 0x0000 | 00001 | STOP |
| 0x0001 | 00002 | START1 |
| 0x0002 | 00003 | START2 |
| 0x0003 | 00004 | Reset Trips |
| 0x0004 | 00005 | Set Real-Time Clock |
| 0x0005 | 00006 | Clear Data-Logging Records |
| 0x0006 | 00007 | Clear Trip Counters |
| 0x0007 | 00008 | Clear Energy Totals |
| 0x0008 | 00009 | Clear Running Hours |
| 0x0009 | 00010 | Emergency I ² t and Trip Reset |
| 0x000A | 00011 | Select Local Control |
| 0x000B | 00012 | De-select Local Control |
| 0x000C | 00013 | Re-enable Temperature Protection |

For PLCs not supporting Function Code 5, commands can be issued using Function Code 6 or 16. Commands are written to MPS register 6 (Modbus register 40007). Use the command codes listed in Table 3. For Function Code 16, the first data element is interpreted as the command code and subsequent bytes are ignored.

3.2 REGISTER DATABASE

Appendix E in the MPS manual contains the Modbus Register Table. The table starts at register 0 (Modbus 40001) and each register is 16-bits wide. Types “long” and “float” are 32-bit values. For both long and float types, the low-order word is transmitted first followed by the high-order word. Word values have the high byte followed by the low byte. Float types are per the IEEE 754 Floating-Point Standard. All bytes of long and float types must be written using one message or an error will result. This does not apply for read commands.

3.3 READING DATA RECORDS

Event record information is located starting at MPS register 973 (Modbus 40974).

Only one event record can be read at a time. Record data is for the record indicated by the Record Selector. To select a record, write the record number to Record Selector with the first message and then read the values in the record with a second message. Record Head points to the next available record. The last event record captured is at Record Head minus one.

The Record Selector must be in the range of 0 to 63. Values outside this range will select record 0.

3.4 USER-DEFINED REGISTERS

User-Defined Registers are used to assemble data in groups in order to minimize the amount of message requests. User-Defined Register values are entered using the *Setup / Hardware / Network Comms / User Register* menu, by using SE-Comm-RIS, or by using network communication messages.

The values entered are the MPS register numbers corresponding to the required parameter as listed in the MPS Manual Appendix E. The entered values are accessible from the menu or via communications by reading the register values starting at MPS register 1400 (Modbus 41401).

The data corresponding to these register values is retrieved by reading the values starting at registers 1432 (Modbus 41433). Data format is a function of the associated MPS register type.

Typically, for PLC communications it is desirable to define data assemblies that are grouped by data type (float or integer). A single read can then access all required float values while another read can access the integer values.

For example, to access the three phase currents enter 860, 861, 862, 863, 864, and 865 in User Register 0 to 5. In a similar manner, the trip summary, motor status, starter status, and Message 0 can be read by entering 1096, 1097, 1098, 1104 in the next available user-register locations starting at User Register 6. The resulting values can be read starting at MPS Register 1432 (Modbus 41433).

3.5 TIMEOUT PREVENTION

To prevent a timeout trip on the MPS, a valid Modbus TCP request addressed to the specific slave is required. This can be a read or write request.

3.6 ERROR RESPONSES

Errors can originate from the hardware or communications software. When a hardware error occurs, “Anybus Error!” is displayed in the *Metering / Network Status* menu, along with an error code. If errors persist, contact the factory.

The MPS supports the following Modbus TCP communication error responses:

- 01: Illegal Function—The function code sent to the MPS server is not supported.
- 02: Illegal Data Address—The requested address is not within the data address range in the MPS.
- 03: Illegal Data Value—Data value is not within the required range.

4. SPECIFICATIONS

| | |
|---------------------------------|------------------------------------------------|
| Interface | 10BASE-T, 100BASE-T, Cat. 3, 4, 5, UTP, STP |
| Protocol | Modbus TCP or EtherNet/IP |
| Baud Rate..... | 10/100 Mbps |
| Number of Slaves Connected..... | Up to 254 units |
| Number of Connections | Up to five |
| Bus length | 100 m (328') per segment |

PART B: ETHERNET/IP

1. GENERAL

This document describes the EtherNet/IP features supported by the MPS. The MPS supports Explicit and Polled I/O. It does not support the Unconnected Message Manager (UCMM).

Starting with version 2.50, setting the IP address, mask, and gateway are done using an OPI menu selection and does not require the “IPConfig” configuration software. This applies to both Modbus TCP and EtherNet/IP versions.

2. ETHERNET PROTOCOL

2.1 PROTOCOL SETUP

The protocol type, IP address, IP Mask, and default gateway are set in the *Setup / Hardware / Network Comms* menu.

For legacy applications or to support EtherNet/IP, select the network type as *Anybus*.

Starting with MPS Version 2.50 IPConfig⁽¹⁾ is not required because the IP Address, Mask, and gateway are set using the *Ethernet IP* and *Ethernet Mask* menu settings, however, IPConfig can still be used to determine the IP Address, Mask, and gateway settings for connected devices.

2.2 LED INDICATION

The module contains four LED indicators as shown in Fig. 2.

LED 1 - Link

Indicates that the module is connected to an Ethernet network.

TABLE 4 LED 2 - MODULE STATUS

| STATE | DESCRIPTION |
|--------------------|--------------------|
| Steady Off | No Power |
| Steady Green | Device Operational |
| Flashing Green | Standby |
| Flashing Red | Minor Fault |
| Steady Red | Major Fault |
| Flashing Green/Red | Self-Test |

TABLE 5 LED 3 - NETWORK STATUS

| STATE | DESCRIPTION |
|--------------------|---------------------------|
| Steady Off | No Power or No IP Address |
| Steady Green | Connected |
| Flashing Green | No Connections |
| Flashing Red | Connection Timeout |
| Steady Red | Duplicate IP |
| Flashing Green/Red | Self-Test |

LED 4 - Activity LED

Flashes green each time a packet is received or transmitted.

2.3 COMMUNICATION STATUS AND TIMEOUT

The status of the Ethernet communication module is indicated as “Ethernet: ONLINE” when the module is operating properly, and as “Ethernet: OFFLINE” when the module is not operating properly. Module errors require the module to be reinitialized. The module is initialized on power up or can be initialized using the OPI. To initialize the module using the OPI, first disable the module by selecting *None* in the *Setup / Hardware / Network Type* menu and then select *Anybus* to enable the module.

In applications where the MPS start/stop functions are controlled by the network, the MPS can be configured to trip or alarm on loss of communication to the module. This feature is enabled using the *Setup / Hardware / Network Comms / Network Error* menu.

To prevent a timeout trip when using the *Anybus* selection (legacy Modbus TCP or EtherNet/IP), see Section 3.3.

2.4 FILE SYSTEM

The module contains a file system that may be useful for storing files associated with the MPS. The file system is a fixed-size storage area with a hierarchical directory structure.

The file system is accessible via FTP, Telnet, HTTP.

The file system is case sensitive. This means that the file ‘AnyBus.txt’ is not identical to the file ‘AnyBus.TXT’. Filenames can be a maximum of 48 characters long. Pathnames can be 256 characters in total, filename included.

NOTES:

- (1) Although IPConfig software can still be used to set the IP address, mask and gateway, these settings are temporary and overwritten by the menu-system value when the MPS Ethernet driver is re-started during powerup or when network parameters are changed.
- (2) The communication address is defined by the MPS *Ethernet IP* setting and is unique for each MPS. The *Network ID* setting is ignored by the MPS. The Modbus broadcast address of 255 is not supported.
- (3) Communications options are mutually exclusive. The RS-485 interface is enabled only when Modbus RTU is selected.
- (4) Select *Anybus* or *Modbus TCP*, only if the MPS has the Ethernet option installed (MPS-CTU-04-XX).

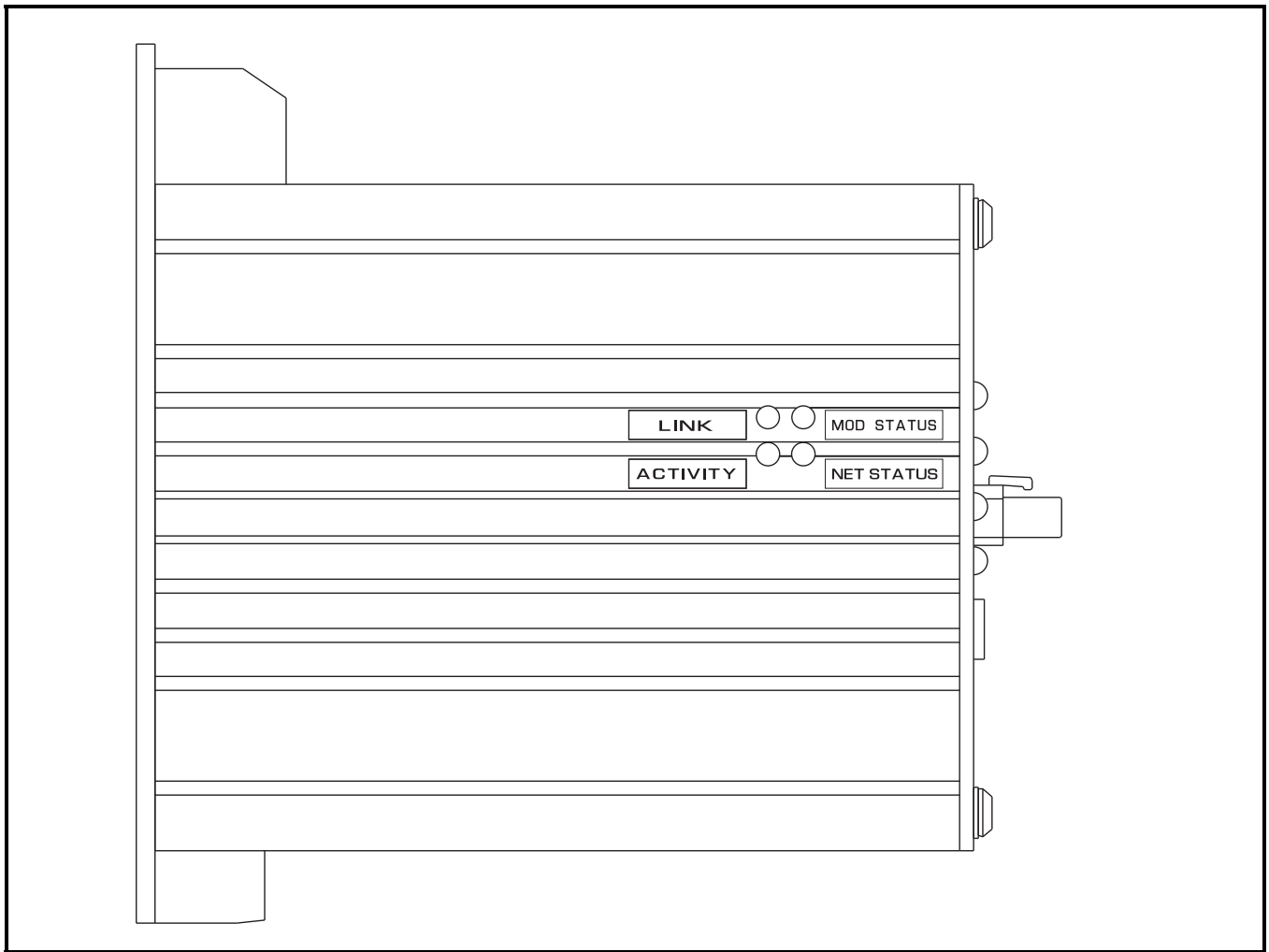


FIGURE 2. MPS-CTU Side View Showing LED's.

3. ETHERNET/IP

This section contains information relative to operation using the *Anybus* protocol selection which supports EtherNet/IP.

The MPS is a slave (server) on the network. It cannot initiate communication.

Up to 5 clients can be connected simultaneously to a single MPS server.

NOTE: The *Anybus* selection is required to support EtherNet/IP and legacy Modbus TCP.

EtherNet/IP uses INPUT and OUTPUT assemblies to transfer data. Input assemblies are used to transfer data from the MPS to the network, and OUTPUT assemblies are used to transfer data from the network to the MPS.

The INPUT assembly consists of 64 bytes representing user-defined data. User defined data is configured by entering the required MPS register numbers in the User Defined Register block using the MPS menu system *Setup | Hardware | Network Comms | User Registers* or by using SE-Comm-RIS program. The format of the data in the assembly is a function of the associated MPS Register. For register definitions and formats see MPS manual Appendix E and F. For example, to access the first four RTD temperatures in RTD Module 1, enter register numbers 902, 903, 904, 905, 906, 907, 908, 909 in the User Defined data area. In the resulting assembly, the first 8 words (16 bytes) will contain the four float values of the RTD temperatures. The remaining values are a function of the corresponding User Register pointers and can be any type. To prevent a read error, unused User Defined data must be set to a valid MPS Register number or zero. Byte order for 16- and 32- bit values follows the convention for the specific protocol and may not be the same as indicated in MPS Appendix E, however, register numbers for float values are still entered in sequence as per the example above.

The OUTPUT area contains a 4-word (8-byte) memory buffer that is used to send control commands to the MPS. This memory has read/write access from the network. Network output is sent to this buffer and the buffer is read by the MPS.

The first word in the buffer (byte 0,1) is the Request Header. This value is used to identify the message as a control-command request. A transition from 0 to 3 indicates a control command. For control commands, the second word is one of the values listed in Table 6.

TABLE 6 MPS COMMAND TABLE

| COMMAND CODE | ACTION |
|--------------|----------------------------------|
| 0x0000 | STOP |
| 0x0001 | START1 |
| 0x0002 | START2 |
| 0x0003 | Reset Trips |
| 0x0004 | Set Real-Time Clock |
| 0x0005 | Clear Data-Logging Records |
| 0x0006 | Clear Trip Counters |
| 0x0007 | Clear Energy Totals |
| 0x0008 | Clear Running Hours |
| 0x0009 | Emergency I't and Trip Reset |
| 0x000A | Select Local Control |
| 0x000B | De-select Local Control |
| 0x000C | Re-enable Temperature Protection |

The command buffer should be written using a single message, however, in some cases where a configuration tool is used, individual bytes may be sent as they are entered. For these applications, the low byte of the Request Header must be sent last and only after all other bytes have been entered.

NOTE: It may be more convenient to send control commands using Explicit Messaging. See Section 4.2 Attribute 100.

3.1 ETHERNET/IP INPUT DATA OBJECT READ

INPUT data is read by a GetSingleAttribute service to Class 4, Instance 100, Attribute 3. Byte order for 16- and 32- bit values follows the convention for the EtherNet/IP protocol and is not the same as indicated in MPS Appendix E. In any case, float value registers should be listed as two registers in sequence (902, 903...).

3.2 ETHERNET/IP OUTPUT DATA OBJECT WRITE

The OUTPUT assembly (memory buffer) is written using the SetSingleAttribute to assembly Class 4, Instance 150, Attribute 3. The Control Command Assembly is shown in Table 7.

TABLE 7 ETHERNET/IP CONTROL COMMAND ASSEMBLY

| BYTE NUMBER | DESCRIPTION |
|-------------|-----------------------|
| 0 | Request Header (Low) |
| 1 | Request Header (High) |
| 2 | MPS Command (Low) |
| 3 | MPS Command (High) |
| 4-7 | Not used |

3.3 TIMEOUT PREVENTION

The MPS can be configured to trip or alarm on loss of communication using the *Setup | Hardware | Network Comms* menu.

To prevent a trip or alarm, an Explicit Message must be sent to any Class other than the Assembly Class, or new data must be written to the OUTPUT memory buffer at an interval less than the MPS trip time of 3 seconds. The suggested method is to use the Control Command format. At regular intervals write an incrementing value to the Command word (bytes 2,3) while keeping the Request Header word (bytes 0,1) at 0. Keeping the Request Header at 0 prevents the MPS from interpreting the Command data as a valid control command.

Incrementing the Command word ensures that a “changed data” event is posted to indicate valid communications. Reading data from the I/O area of the module is not sufficient to satisfy the time-out timer.

Communication status is displayed in the *Metering / Comm State* menu.

Writes to the OUPUT memory buffer are indicated by “Output: NO” or “Output: YES”. If the module is receiving output from the network, then “Output YES” will be displayed.

3.4 NETWORK CONFIGURATION FILES

For EtherNet/IP, an eds file is available from www.anybus.com. As part of the network configuration, the input and output assembly size may need to be specified. The INPUT assembly size is fixed at 64 bytes and the OUTPUT assembly size is 8 bytes.

This document does not describe the specific objects required to support the EtherNet/IP protocol. For details on these objects, see the Anybus-S documentation at www.anybus.com.

3.5 RSLOGIX5000 SETUP

Add a Generic Ethernet Module as a New Module to the PLC. The comm. Format for the MPS is Data-INT. The Input Assembly Instance is 100 with a size of 32. The Output Assembly Instance is 150 with a size of 4 and the Configuration Assembly Instance is 1 with a size of 0.

4. CLASSES

4.1 IDENTITY OBJECT 0x01

Identity Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Identity Class (1), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

Identity Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modify the specified attribute.

Identity Class (1), Instance (1) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|------------------------------------------|---------------------------|--------------|---------------|
| 1 | Vendor ID | Get | Identification of each vendor by number. | 691 | UINT | |
| 2 | Device Type | Get | Communications | 12 | UINT | |
| 3 | Product Code | Get | Platform Type Adapter | 201 | UINT | 0 |
| 4 | Revision | Get | Major revision must match the EDS value. | 4.100 | A2 02 C6 C6 | |
| 5 | Status | Get | Summary status of the device. | 0, 0, 255 | WORD | |
| 6 | Serial Number | Get | Serial Number of the Anybus Module. | N/A, 0, 999999999 | UDINT | |
| 7 | Product Name | Get | Human Readable Identification | "Startco MPS" | SHORT_STRING | |

4.2 CONTROL SUPERVISOR 0x29

Control Supervisor Class (0x29), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

Supervisor Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

Supervisor Class (0x29), Instance (1) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|------------------------|----------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 100 (0x64) | Command | Get/Set | A command "Set" will cause the requested command to be issued. A "Get" will read the last command. 0 = Stop 1 = Start 1 2 = Start 2 3 = Reset Trips 4 = Set RTC 5 = Clear Data Logging Records 6 = Clear Trips Counters 7 = Clear Energy Totals 8 = Clear Running Time 9 = Emergency I ² t Reset 10 = Select Local-Input Ctrl 11 = Release Local-Input Ctrl 12 = Re-enable Temperature Protection | 0, 0, 12 | USINT | |
| 101 (0x65) | DIF Enable | Get/Set | Differential Module Enable | 0,0,1 | UINT | 1277 |
| 102 (0x66) | DIF Error Trip Action | Get/Set | DIF Module Error trip action: 0 = Disable 1 = Trip1 2 = Trip2 3 = Trip3 4 = Trip1 & Trip2 5 = Trip1 & Trip3 6 = Trip1 & Trip2 & Trip3 7 = Trip2 & Trip3 | 0,0,7 | UINT | 1278 |
| 103 (0x67) | DIF Error Alarm Action | Get/Set | DIF Module Error alarm action: 0 = Disable 1 = Alarm1 2 = Alarm2 3 = Alarm3 4 = Alarm1 & Alarm2 5 = Alarm1 & Alarm3 6 = Alarm1 & Alarm2 & Alarm3 7 = Alarm2 & Alarm3 | 0,0,7 | UINT | 1279 |
| 104 (0x68) | DIF Error Trip Count | Get | Module Error Trip Count | | UINT | 1194 |
| 105(0x69) | Reserved | | | | | |
| 106 (0x6A) | Trip Action | Get/Set | OPI Loss Trip Action: 0 = Disable 1 = Trip1 2 = Trip2 3 = Trip3 4 = Trip1 & Trip2 5 = Trip1 & Trip3 6 = Trip1 & Trip2 & Trip3 7 = Trip2 & Trip3 | 0, 0, 7 | UINT | 237 |
| 107 (0x6B) | # of OPI's | Get/Set | Selects the number of OPI's connected to the control unit. | 1, 0, 3 | UINT | 238 |
| 108 (0x6C) | OPI Remote | Get/Set | 0 = Enable OPI to Select REMOTE 1 = OPI Cannot Select REMOTE | 0, 0, 1 | UINT | 239 |
| 109 (0x6D) | OPI Control | Get/Set | 0 = Enable OPI Motor Control 1 = Disable OPI Motor Control | 0, 0, 1 | UINT | 240 |
| 110 (0x6E) | OPI Local | Get/Set | 0 = Enable OPI to Select LOCAL 1 = OPI Cannot Select LOCAL | 0, 0, 1 | UINT | 241 |
| 111 (0x6F) | OPI Trips | Get | Number of OPI Comm Trips | | UINT | 1185 |

Supervisor Class (0x29), Instance (1) Attributes (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------|----------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 112 (0x70) | RemGrpDig | Get/ Set | Bind digital start sources to the REMOTE group. 0 = Include in Group 1 = Do Not Include in Group | 0, 0, 1 | UINT | 242 |
| 113 (0x71) | RemGrpNet | Get/Set | Bind OPI start sources to the REMOTE group. 0 = Include in Group 1 = Not in Group | 0, 0, 1 | UINT | 243 |
| 114 (0x72) | RemGrpOPI | Get/Set | Bind Net start sources to the REMOTE group. 0 = Include in Group 1 = Not in Group | 0, 0, 1 | UINT | 244 |
| 115 (0x73) | Starter Type | Get/Set | Selects the starter type: 0 = Protection Only 1 = Full Voltage Non-Reversing 2 = Adjustable-Speed Drive 3 = Soft Start 4 = Full Voltage Reversing 5 = Two Speed * 6 = Reactor/Resistor Closed Transition 7 = Reactor/Resistor Open Transition 8 = Slip Ring 9 = Soft Start With Bypass 10 = Port Winding * 11 = Double Delta * 12 = Autotransformer 13 = Two Winding * 14 = Wye-Delta Open Trans. * 15 = Wye-Delta Closed Trans. * * Uses Full-Load Current 2 | 0, 0, 15 | UINT | 248 |
| 116 (0x74) | Start Time | Get/Set | See Main Product Manual | 20, 0.1, 500 | REAL | 249/250 |
| 117 (0x75) | Start Delay 1 | Get/Set | See Main Product Manual | 20, 0.1, 500 | REAL | 251/252 |
| 118 (0x76) | Start Delay 2 | Get/Set | See Main Product Manual | 20, 0.1, 500 | REAL | 253/254 |
| 119 (0x77) | Start Delay 3 | Get/Set | See Main Product Manual | 20, 0.1, 500 | REAL | 255/256 |
| 120 (0x78) | Backspin Enable | Get/Set | 0 = Backspin Timer Enabled 1 = Backspin Timer Disabled | 1, 0, 1 | UINT | 257 |
| 121 (0x79) | Backspin Delay | Get/Set | Backspin Delay in Seconds | 5, 0.1, 100 | REAL | 258/259 |
| 122 (0x7A) | Sequence Trips | Get | Number of Starter Sequence Trips | | UINT | 1184 |
| 123 (0x7B) | Stop Count | Get | Number of trips caused by STOP when starter type is set to Protection Only. | | UINT | 1186 |
| 124 (0x7C) | RY Status Trips | Get | Number of Contactor Status Trips | | UINT | 1148 |
| 125 (0x7D) | Transfer Type | Get/Set | Soft-Start Transfer Type 0 = Time Transfer 1 = Current Transfer | 0, 0, 1 | UINT | 260 |
| 126 (0x7E) | Transfer Level | Get/Set | Level in % FLA | 1.25, 1.0, 3.0 | REAL | 261/262 |
| 127(0x7f) | Reserved | | | | | |

Supervisor Class (0x29), Instance (1) Attributes (Continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 128 (0x80) | RY1 Function | Get/Set | Function Assigned to Relay 1: 0 = None 1 = Starter RLYA 2 = Starter RLYB 3 = Starter RLYC 4 = Starter RLYD 5 = Trip1 6 = Alarm1 7 = Aux 8 = Interlock 9 = Local 10 = Current Detected 11 = Run Mode 12 = Start Sequence Complete 13 = Thermal Lockout 14 = None 15 = Watchdog 16 = Trip3 17 = Alarm2 18 = Alarm3 19 = Trip1 Pulse 20 = Reduced OC | 0, 0, 20 | UINT | 334 |
| 129 (0x81) | RY1 Mode | Get/Set | 0 = Fail Safe, 1 = Non Fail Safe | 0, 0, 1 | UINT | 335 |
| 130 (0x82) | RY2 Function | Get/ Set | See Attribute 0x80 | 0, 0, 20 | UINT | 336 |
| 131 (0x83) | RY2 Mode | Get/Set | 0 = Fail Safe, 1 = Non Fail Safe | 0, 0, 1 | UINT | 337 |
| 132 (0x84) | RY3 Function | Get/ Set | See Attribute 0x80 | 0, 0, 20 | UINT | 338 |
| 133 (0x85) | RY3 Mode | Get/Set | 0 = Fail Safe, 1 = Non Fail Safe | 0, 0, 1 | UINT | 339 |
| 134 (0x86) | RY4Function | Get/ Set | See Attribute 0x80 | 0, 0, 20 | UINT | 340 |
| 135 (0x87) | RY4 Mode | Get/Set | 0 = Fail Safe, 1 = Non Fail Safe | 0, 0, 1 | UINT | 341 |
| 136 (0x88) | RY5 Function | Get/ Set | See Attribute 0x80 | 0, 0, 20 | UINT | 342 |
| 137 (0x89) | RY5 Mode | Get/Set | 0 = Fail Safe, 1 = Non Fail Safe | 0, 0, 1 | UINT | 343 |
| 138 (0x8A) | RY Pulse Time | Get/Set | Specifies the duration of the trip pulse when the RY function is set to "Trip1 Pulse". | 0.25, 0.05, 10 | REAL | 344 |
| 144 (0x90) | TA Summary | Get | Trip, Alarm, Status Summary Bit 0: 1 = Trip (Trip1 or Trip3) Bit 1: 1 = Alarm (Alarm 1, 2, 3) Bit 2: 1 = Trip2 Bit 3: 1 = Interlocks Not Valid Bit 4: 1 = Start Lock Active Bit 5: 1 = Stop Input Active | | WORD | 1096 |
| 145 (0x91) | Motor Status | Get | Bit 0: 1 = I > Threshold Bit 1: 1 = 10% < I < 125% for 10 s Bit 2: 1 = Tach at Full Speed Bit 3: 1 = I > 120% FLA Bit 4: 1 = Temperature Bypassed Bit 5: 1 = Reduced OC On | | WORD | 1097 |
| 146 (0x92) | Starter Status | Get | 1 = Start 1 2 = Run 1 (Sequence Complete) 3 = Start 2 4 = Run 2 (Sequence Complete) 5 = Stop 6 = Backspin Timer Active | | UINT | 1098 |

Supervisor Class (0x29), Instance (1) Attributes (Continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|------------------|----------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|--------------|---------------|
| 147 (0x93) | Digital Inputs | Get | Bit 0: IN1 Voltage Detected Bit 1: IN2 Voltage Detected Bit 2: IN3 Voltage Detected Bit 3: IN4 Voltage Detected Bit 4: IN5 Voltage Detected Bit 5: IN6 Voltage Detected Bit 6: IN7 Voltage Detected | | WORD | 1099 |
| 148 (0x94) | Relay Outputs | Get | Bit 0: Relay 1 Energized Bit 1: Relay 2 Energized Bit 2: Relay 3 Energized Bit 3: Relay 4 Energized Bit 4: Relay 5 Energized | | WORD | 1100 |
| 149..151 | Reserved | | | | | |
| 152 (0x98) | Trip/Alarm Msg 0 | Get | Trip and Alarm FIFO. See Main Product Manual Appendix F T27. 255= No trip or alarm. | | UINT | 1104 |
| 153 (0x99) | Trip/Alarm Msg 1 | Get | Trip and Alarm FIFO. See Main Product Manual Appendix F T27. 255= No trip or alarm. | | UINT | 1105 |
| 154 (0x9A) | Trip/Alarm Msg 2 | Get | Trip and Alarm FIFO. See Main Product Manual Appendix F T27. 255= No trip or alarm. | | UINT | 1106 |
| 155 (0x9B) | Trip/Alarm Msg 3 | Get | Trip and Alarm FIFO. See Main Product Manual Appendix F T27. 255= No trip or alarm. | | UINT | 1107 |
| 156 (0x9C) | Trip/Alarm Msg 4 | Get | Trip and Alarm FIFO. See Main Product Manual Appendix F T27. 255= No trip or alarm. | | UINT | 1108 |
| 157 (0x9d) | Revision | Get | Revision of Firmware 100 = 1.00 | N/A, 100, N/A | UINT | 1 |
| 158 (0x9e) | System Name | Get/Set | 22 characters. Only 20 significant. | “Startco MPS” | SHORT_STRING | 600 |
| 159 (0x9f) | Password | Get/Set | 22 characters. Only 4 significant. | “1111” | SHORT_STRING | 590 |

4.3 OVERLOAD CLASS 0x2C
Overload Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Overload Class (0x2C), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

Overload Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modify specified attribute.

Overload Class (0x2C), Instance (1) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|--------------------|----------|------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 100 (0x64) | Trip Action | Get/Set | 0 = Disable 1 = Trip1 2 = Trip2 3 = Trip3 4 = Trip1 & Trip2 5 = Trip1 & Trip3 6 = Trip1 & Trip2 & Trip3 7 = Trip2 & Trip3 | 1, 0, 7 | UINT | 8 |
| 101 (0x65) | Thermal Model | Get/Set | 0 = NEMA 1 = I ² t | 0, 0, 1 | UINT | 9 |
| 102 (0x66) | Start Inhibit | Get/Set | Inhibits Start if I ² t < Thermal Lockout Level 0 = Enable 1 = Disable | 1, 0, 1 | UINT | 10 |
| 103 (0x67) | K-Factor | Get/Set | Used in I ² t Algorithm | 6, 1, 10 | REAL | 11/12 |
| 104 (0x68) | LR Current | Get/Set | Locked Rotor Current (x FLA) | 6, 1, 10 | REAL | 12/14 |
| 105 (0x69) | LR Time Cold | Get/Set | Locked Rotor Time Cold (s) | 10, 0.2, 100 | REAL | 15/16 |
| 106 (0x6A) | LR Time Hot | Get/Set | Locked Rotor Time Hot (s) | 5, 0.2, 100 | REAL | 17/18 |
| 107 (0x6B) | Cooling Factor | Get/Set | Multiples of Running Time Constant | 2, 0.1, 50 | REAL | 19/20 |
| 108 (0x6C) | Thermal Lock Level | Get/Set | Thermal Reset/Inhibit Level per Unit | 0.3, 0.1, 0.9 | REAL | 21/22 |
| 109 (0x6D) | Overload Alarm | Get/Set | Level where Alarm Occurs | 1.0, 0.5, 1.0 | REAL | 23/24 |
| 110 (0x6E) | Alarm Action | Get/Set | 0 = Disable 1 = Alarm1 2 = Alarm2 3 = Alarm3 4 = Alarm1 & Alarm2 5 = Alarm1 & Alarm3 6 = Alarm1 & Alarm2 & Alarm3 7 = Alarm2 & Alarm3 | 1, 0, 7 | UINT | 25 |
| 111 (0x6F) | V Connection | Get/Set | Voltage Input Connection 0 = None 1 = 1PT 2 = 2PT 3 = 3PT | 0, 0, 3 | UINT | 209 |
| 112 (0x70) | CT Primary | Get/Set | CT Primary Rating (A) | 100, 1, 5000 | REAL | 210/211 |
| 113 (0x71) | EFCT Primary | Get/Set | EFCT Primary Rating (A) | 5, 1, 5000 | REAL | 212/213 |
| 114 (0x72) | Vin Rating | Get/Set | Input Voltage at Rated System Voltage (kV) | 0.12, 0.03, 0.6 | REAL | 214/215 |
| 115 (0x73) | Frequency | Get/Set | System Frequency: 0 = 50, 1 = 60 Hz | 1, 0, 1 | UINT | 224 |
| 116 (0x74) | FLA Rating 1 | Get/Set | Full-Load Current #1 | 100, 1, 5000 | REAL | 225/226 |
| 117 (0x75) | System Voltage | Get/Set | Line-to-Line Voltage (kV) | 0.6, 0.12, 25 | REAL | 227/228 |
| 118 (0x76) | Sync Speed | Get/Set | Motor Synchronous Speed (RPM) | 1800, 100, 10k | REAL | 229/230 |
| 119 (0x77) | Service Factor | Get/Set | Motor Service Factor | 1, 1, 1.25 | REAL | 233/234 |
| 120 (0x78) | FLA Rating 2 | Get/Set | Full-Load Current #2 | 100, 1, 5000 | REAL | 235/236 |
| 121 (0x79) | Trip Count | Get | Counts Overload Trips | | UINT | 1132 |
| 122 (0x7A) | Run-Mode Delay | Get/Set | Time delay defines when motor is in run mode. | 10, 5, 60 | REAL | 216/217 |
| 123(0x7B) | SPH Trip Action | Get/Set | Starts Per Hour Trip Action. | 0,0,7 | UINT | 1270 |
| 124(0x7C) | SPH Alarm Action | Get/Set | Starts Per Hour Alarm Action | 0,0,7 | UINT | 1271 |

Overload Class (0x2C), Instance (1) Attributes (Continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|---------------------|----------|--------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 125(0x7D) | Starts Per Hour | Get/Set | Starts Per Hour setting: 0= 1 Start Per Hour 9= 10 Starts Per Hour | 4,0,9 | UINT | 1272 |
| 126(0x7E) | Time Between Starts | Get/Set | Time in minutes between starts. | 0,0,500 | REAL | 1273/1274 |
| 127(0x7F) | SPH Trip Count | Get | Number of SPH trips. | | UINT | 1193 |
| 128(0x80) | Overload Reset Type | Get/Set | Thermal Overload Reset Type | 0,0,2 | UINT | 26 |
| | | | | | | |
| 144 (0x90) | I _A | Get | Phase A Current (A) | | REAL | 860/861 |
| 145 (0x91) | I _B | Get | Phase B Current (A) | | REAL | 862/863 |
| 146 (0x92) | I _C | Get | Phase C Current (A) | | REAL | 864/865 |
| 147 (0x93) | 3I _O | Get | Ground-Fault Current (A) | | REAL | 866/867 |
| 148 (0x94) | V _{ab} | Get | Line-to-Line Voltage (kV) | | REAL | 868/869 |
| 149 (0x95) | V _{bc} | Get | Line-to-Line Voltage (kV) | | REAL | 870/871 |
| 150 (0x96) | V _{ca} | Get | Line-to-Line Voltage (kV) | | REAL | 872/873 |
| 151 (0x97) | S | Get | Apparent Power (kVA) | | REAL | 874/875 |
| 152 (0x98) | Q | Get | Reactive Power (kVAC) | | REAL | 876/877 |
| 153 (0x99) | P | Get | Real Power (kW) | | REAL | 878/879 |
| 154 (0x9A) | PF | Get | Power Factor | -1 to +1 | REAL | 880/881 |
| 155 (0x9B) | Used I _t | Get | Used Thermal Capacity (%) | | REAL | 882/883 |
| 156 (0x9C) | Thermal Trend | Get | Thermal Trend (%) | | REAL | 886/887 |
| 157 (0x9D) | +Seq I | Get | Positive Sequence Current (Pu) | | REAL | 888/889 |
| 158 (0x9E) | -Seq I | Get | Negative Sequence Current (Pu) | | REAL | 890/891 |
| 159 (0x9F) | Unbalance I | Get | Current Unbalance (Pu) | | REAL | 892/893 |
| 160 (0xA0) | Frequency | Get | Frequency (from Vab) | | REAL | 966/967 |
| 161 (0xA1) | -Seq V | Get | Negative Sequence Voltage (Pu) | | REAL | 896/897 |
| 162 (0xA2) | Unbalance V | Get | Voltage Unbalance (Pu) | | REAL | 898/899 |
| 163 (0xA3) | Run Time | Get | Running Time in Seconds | | UDINT | 1210 |
| 164 (0xA4) | KWs | Get | KW Seconds | | LREAL | 1212..15 |
| 165 (0xA5) | KVAs | Get | KVA Seconds | | LREAL | 1216..19 |
| 166 (0xA6) | KVARs | Get | KVAR Seconds | | LREAL | 1220..23 |
| 167(0xA7) | DIF Ia | Get | Differential Current, Phase A | | REAL | 1224/1225 |
| 168(0xA8) | DIF Ib | Get | Differential Current, Phase B | | REAL | 1226/1227 |
| 168(0xA9) | DIF Ic | Get | Differential Current, Phase C | | REAL | 1228/1229 |

4.4 SET POINT CLASS 0x64
Set Point Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Set Point Class (0x64), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 5 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 22 | UINT |

Set Point Object Instances

Set Point Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

The set point class consists of seven attributes. Each set-point instance may use some or all of these attributes.

Attribute 1 - Trip Action

Specifies the action to take on a trip.

0 = Disable

1 = Trip1 ⁽¹⁾

2 = Trip2

3 = Trip3

4 = Trip1 & Trip2

5 = Trip1 & Trip3

6 = Trip1 & Trip2 & Trip3

7 = Trip2 & Trip3

Attribute 2 - Alarm Action

Specifies the action to take on an alarm.

0 = Disable

1 = Alarm1

2 = Alarm2

3 = Alarm3

4 = Alarm1 & Alarm2

5 = Alarm1 & Alarm3

6 = Alarm1 & Alarm2 & Alarm3

7 = Alarm2 & Alarm3

Attribute 3 - Trip Level

Attribute 4 - Trip Delay

Attribute 5 - Alarm Level

Attribute 6 - Alarm Delay

Attribute 7 - Trip Counter for the set point

⁽¹⁾ Initiates a STOP when a starter function is enabled

Class 0x64, Instance 1 - Overcurrent

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 32 |
| 3 | Trip Level | Get/Set | 10, 1, 15 | REAL | 33/34 |
| 4 | Trip Delay | Get/Set | 0.1, 0, 10 | REAL | 35/36 |
| 7 | Trip Count | Get | | UINT | 1130 |

Class 0x64, Instance 2 - Aux. Overcurrent

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 40 |
| 3 | Trip Level | Get/Set | 10, 1, 15 | REAL | 41/42 |
| 4 | Trip Delay | Get/Set | 0.1, 0, 10 | REAL | 43/44 |
| 7 | Trip Count | Get | | UINT | 1131 |

Class 0x64, Instance 3 - Earth Fault

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 48 |
| 2 | Alarm Action | Get/Set | 1, 0, 7 | UINT | 58 |
| 3 | Trip Level | Get/Set | 0.4, 0.05, 1 | REAL | 50/51 |
| 4 | Trip Delay | Get/Set | 0.25, 0, 100 | REAL | 52/53 |
| 5 | Alarm Level | Get/Set | 0.20, 0.05, 1 | REAL | 54/55 |
| 6 | Alarm Delay | Get/Set | 1, 0, 100 | REAL | 56/57 |
| 7 | Trip Count | Get | | UINT | 1133 |

Class 0x64, Instance 4 - Jam

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 64 |
| 2 | Alarm Action | Get/Set | 1, 0, 7 | UINT | 73 |
| 3 | Trip Level | Get/Set | 6, 1, 10 | REAL | 65/66 |
| 4 | Trip Delay | Get/Set | 5, 1, 100 | REAL | 67/68 |
| 5 | Alarm Level | Get/Set | 3, 1, 10 | REAL | 69/70 |
| 6 | Alarm Delay | Get/Set | 5, 1, 100 | REAL | 71/72 |
| 7 | Trip Count | Get | | UINT | 1136 |

Class 0x64, Instance 5 - Current Unbalance (I)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 80 |
| 2 | Alarm Action | Get/Set | 1, 0, 7 | UINT | 89 |
| 3 | Trip Level | Get/Set | 0.25, 0.05, 1 | REAL | 81/82 |
| 4 | Trip Delay | Get/Set | 15, 1, 100 | REAL | 83/84 |
| 5 | Alarm Level | Get/Set | 0.10, 0.05, 1 | REAL | 85/86 |
| 6 | Alarm Delay | Get/Set | 10, 1, 100 | REAL | 87/88 |
| 7 | Trip Count | Get | | UINT | 1134 |

Class 0x64, Instance 6 - Phase Reverse (I)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|---------------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 96 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 95 |
| 4 | Phase Reverse Delay | Get/Set | 2, 1, 100 | REAL | 97/98 |
| 7 | Trip Count | Get | | UINT | 1144 |
| | | | | | |

Class 0x64, Instance 7 - Phase Loss (I)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|------------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 99 |
| 4 | Phase Loss Delay | Get/Set | 5, 1, 100 | REAL | 100/101 |
| 7 | Trip Count | Get | | UINT | 1143 |

Class 0x64, Instance 8 - Voltage Unbalance

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 104 |
| 2 | Alarm Action | Get/Set | 1, 0, 7 | UINT | 113 |
| 3 | Trip Level | Get/Set | 0.1, 0.05, 1 | REAL | 105/106 |
| 4 | Trip Delay | Get/Set | 15, 1, 100 | REAL | 107/108 |
| 5 | Alarm Level | Get/Set | 0.05, 0.05, 1 | REAL | 109/110 |
| 6 | Alarm Delay | Get/Set | 10, 1, 100 | REAL | 111/112 |
| 7 | Trip Count | Get | | UINT | 1135 |

Class 0x64, Instance 9 - Phase Reverse (V)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|---------------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 120 |
| 4 | Phase Reverse Delay | Get/Set | 2, 1, 100 | REAL | 121/122 |
| 7 | Trip Count | Get | | UINT | 1146 |

Class 0x64, Instance 0x0A - Phase Loss (V)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|------------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 123 |
| 4 | Phase Loss Delay | Get/Set | 5, 1, 100 | REAL | 124/125 |
| 7 | Trip Count | Get | | UINT | 1145 |

Class 0x64, Instance 0x0B - Undercurrent

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 128 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 137 |
| 3 | Trip Level | Get/Set | 0.5, 0.1, 1 | REAL | 129/130 |
| 4 | Trip Delay | Get/Set | 10, 1, 100 | REAL | 131/132 |
| 5 | Alarm Level | Get/Set | 0.8, 0.1, 1 | REAL | 133/134 |
| 6 | Alarm Delay | Get/Set | 20, 1, 100 | REAL | 135/136 |
| 7 | Trip Count | Get | | UINT | 1137 |

Class 0x64, Instance 0x0C - PTC Temperature

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 144 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 145 |
| 7 | Trip Count | Get | | UINT | 1145 |

Class 0x64, Instance 0x0D - Overvoltage

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 1, 0, 7 | UINT | 176 |
| 2 | Alarm Action | Get/Set | 1, 0, 7 | UINT | 185 |
| 3 | Trip Level | Get/Set | 1.2, 1, 1.4 | REAL | 177/178 |
| 4 | Trip Delay | Get/Set | 5, 1, 500 | REAL | 179/180 |
| 5 | Alarm Level | Get/Set | 1.1, 1, 1.4 | REAL | 181/182 |
| 6 | Alarm Delay | Get/Set | 5, 1, 500 | REAL | 183/184 |
| 7 | Trip Count | Get | | UINT | 1138 |

Class 0x64, Instance 0x0E - Undervoltage

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 192 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 201 |
| 3 | Trip Level | Get/Set | 0.7, 0.5, 1 | REAL | 193/194 |
| 4 | Trip Delay | Get/Set | 5, 1, 500 | REAL | 195/196 |
| 5 | Alarm Level | Get/Set | 0.8, 0.5, 1 | REAL | 197/198 |

Class 0x64, Instance 0x0E – Undervoltage (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 6 | Alarm Delay | Get/Set | 5, 1, 500 | REAL | 199/200 |
| 7 | Trip Count | Get | | UINT | 1139 |

Class 0x64, Instance 0x0F - Underfrequency

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 1230 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 1248 |
| 3 | Trip Level | Get/Set | 45, 30, 80 | REAL | 1231/1232 |
| 4 | Trip Delay | Get/Set | 5, 0.5, 500 | REAL | 1233/1234 |
| 5 | Alarm Level | Get/Set | 48, 30, 80 | REAL | 1235/1236 |
| 6 | Alarm Delay | Get/Set | 1, 0.5, 500 | REAL | 1237/1238 |
| 7 | Trip Count | Get | | UINT | 1188 |

Class 0x64, Instance 0x10 - Overfrequency

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 1239 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 1249 |
| 3 | Trip Level | Get/Set | 65, 30, 80 | REAL | 1240/1241 |
| 4 | Trip Delay | Get/Set | 5, 0.5, 500 | REAL | 1242/1243 |
| 5 | Alarm Level | Get/Set | 62, 30, 80 | REAL | 1244/1245 |
| 6 | Alarm Delay | Get/Set | 1, 0.5, 500 | REAL | 1246/1247 |
| 7 | Trip Count | Get | | UINT | 1189 |

Class 0x64, Instance 0x11 - Power Factor Quadrant 4

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 166 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 175 |
| 3 | Trip Level | Get/Set | 0.8, 0.5, 1 | REAL | 167/168 |
| 4 | Trip Delay | Get/Set | 5, 0.2, 500 | REAL | 169/170 |
| 5 | Alarm Level | Get/Set | 0.9, 0.5, 1 | REAL | 171/172 |
| 6 | Alarm Delay | Get/Set | 5, 0.2, 500 | REAL | 173/174 |
| 7 | Trip Count | Get | | UINT | 1187 |

Class 0x64, Instance 0x12 - Power Factor Quadrant 3

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 1250 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 1259 |
| 3 | Trip Level | Get/Set | 0.8, 0.5, 1 | REAL | 1251/1252 |
| 4 | Trip Delay | Get/Set | 5, 0.2, 500 | REAL | 1253/1254 |
| 5 | Alarm Level | Get/Set | 0.9, 0.5, 1 | REAL | 1255/1256 |
| 6 | Alarm Delay | Get/Set | 5, 0.2, 500 | REAL | 1257/1258 |
| 7 | Trip Count | Get | | UINT | 1192 |

Class 0x64, Instance 0x13 - Differential

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 1280 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 1289 |
| 3 | Trip Level | Get/Set | 1, 0.1, 15 | REAL | 1281/1282 |
| 4 | Trip Delay | Get/Set | 0.1, 0, 10 | REAL | 1283/1284 |
| 5 | Alarm Level | Get/Set | 0.5, 0.1, 15 | REAL | 1285/1286 |
| 6 | Alarm Delay | Get/Set | 0.1, 0, 10 | REAL | 1287/1288 |
| 7 | Trip Count | Get | | UINT | 1195 |

Class 0x64, Instance 0x14 – Reduced Overcurrent

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 45 |
| 3 | Trip Level | Get/Set | 2, 1, 15 | REAL | 46/47 |
| 7 | Trip Count | Get | | UINT | 1196 |

Class 0x64, Instance 0x15 – Underpower

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 1070 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 1079 |
| 3 | Trip Level | Get/Set | 0.8, 0.1, 1.0 | REAL | 1071/1072 |
| 4 | Trip Delay | Get/Set | 5, 0.5, 500 | REAL | 1073/1074 |
| 5 | Alarm Level | Get/Set | 0.2, 0.1, 1.0 | REAL | 1075/1076 |
| 6 | Alarm Delay | Get/Set | 1, 0.5, 500 | REAL | 1077/1078 |
| 7 | Trip Count | Get | | UINT | 1197 |

Class 0x64, Instance 0x16 – Reversepower

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------|-----------|---------------|
| 1 | Trip Action | Get/Set | 0, 0, 7 | UINT | 1080 |
| 2 | Alarm Action | Get/Set | 0, 0, 7 | UINT | 1089 |
| 3 | Trip Level | Get/Set | 0.2, 0.1, 1.0 | REAL | 1081/1082 |
| 4 | Trip Delay | Get/Set | 5, 0.5, 500 | REAL | 1083/1084 |
| 5 | Alarm Level | Get/Set | 0.2, 0.1, 1.0 | REAL | 1085/1086 |
| 6 | Alarm Delay | Get/Set | 1, 0.5, 500 | REAL | 1087/1088 |
| 7 | Trip Count | Get | | UINT | 1198 |

4.5 ACCELERATION CLASS 0x65

Motor speed is measured using a digital tach connected to Digital Input 8, or a 4–20 mA speed sensor. This class defines parameters for speed protection.

Acceleration Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Acceleration Class (0x65), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

Acceleration Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

Instance 1 Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 1 | Accel Action | Get/Set | Specifies the action to take on a trip. 0 = Disable 1 = Trip1 ⁽¹⁾ 2 = Trip2 3 = Trip3 4 = Trip1 & Trip2 5 = Trip1 & Trip3 6 = Trip1 & Trip2 & Trip3 7 = Trip2 & Trip3 ⁽¹⁾ Initiates a STOP when a starter function is enabled. | 0, 0, 7 | UINT | 152 |
| 2 | Speed1 | Get/Set | Motor must reach Speed1 in the time defined by Time1. (%FS) | 30, 1, 100 | REAL | 153/154 |

Instance 1 Attributes (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|----------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 3 | Time1 | Get/Set | Defines the time when Speed1 must be reached. (s) | 5, 1, 1000 | REAL | 155/156 |
| 4 | Speed2 | Get/Set | Motor must reach Speed2 in the time defined by Time2. (%FS) | 60, 1, 100 | REAL | 157/158 |
| 5 | Time2 | Get/Set | Defines the time when Speed2 must be reached. (s) | 10, 1, 1000 | REAL | 159/160 |
| 6 | Speed3 | Get/Set | Motor must reach Speed3 in the time defined by Time3. (%FS) | 90, 1, 100 | REAL | 161/164 |
| 7 | Time3 | Get/Set | Defines the time when Speed3 must be reached. (s) | 15, 1, 1000 | REAL | 163/164 |
| 8 | Tach Enable | Get/Set | Enables speed measurement even if protection is disabled. 0 = Enabled, 1 = Disabled | 1, 0, 1 | UINT | 330 |
| 9 | Pulses Per Rev | Get/Set | Sets the number of pulses per revolution for digital tach. | 60, 1, 100 | REAL | 331/332 |
| 10 (0x0A) | Tach Speed | Get | Motor Speed from Tach | | REAL | 900/901 |
| 11 (0x0B) | Trip Count | Get | Counts Number of Accel Trips | | UINT | 1147 |

4.6 DIGITAL INPUT CLASS 0x66

Digital Input Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Digital Input Class (0x66), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 7 | UINT |

Digital Input Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

The digital-input class consists of 5 attributes.

Attribute 1 - Function

Selects the function of the digital input.

- 0 = Input not used
- 1 = Start1 (N.O. Contact)
- 2 = Start2 (N.O. Contact)
- 3 = Stop (N.C. Contact)
- 4 = Starter RLYA contactor status
- 5 = Starter RLYB contactor status
- 6 = Starter RLYC contactor status
- 7 = Starter RLYD contactor status
- 8 = Interlock (N.C.)
- 9 = Trip1 (N.C.)
- 10 = Reset (N.O.)
- 11 = Local Select
- 12 = Local Start1
- 13 = Local Start2
- 14 = 2-Wire Start1
- 15 = 2-Wire Start2
- 16 = FLA2 Select
- 17 = Limit1 Select
- 18 = Limit2 Select
- 19 = Reduced OC

Attribute 2 - Bypass Enable/Disable

Attribute applies when the input function is trip. When enabled, the input is bypassed for the time defined by the Bypass Delay when a motor is started using starter control. 0 = Enable, 1 = Disable

Attribute 3 - Bypass Delay

Defines the Trip bypass time duration on start.

Attribute 4 - Trip Delay

Applies only to the trip function.

Attribute 5 - Trip Count

The trip counter only applies to the trip function.

Class 0x66, Instance 1 - Input 1

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------------|----------|---------------------------|-----------|---------------|
| 1 | Function | Get/Set | 0, 0, 19 | UINT | 264 |
| 2 | Bypass Enable/Disable | Get/Set | 1, 0, 1 | UINT | 265 |
| 3 | Bypass Delay | Get/Set | 5, 0.5, 100 | REAL | 266/267 |
| 4 | Trip Delay | Get/Set | 0.1, 0.01, 100 | REAL | 268/269 |
| 5 | Trip Counter | Get | | UINT | 1149 |

Class 0x66, Instance 2 - Input 2

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------------|----------|---------------------------|-----------|---------------|
| 1 | Function | Get/Set | 0, 0, 19 | UINT | 274 |
| 2 | Bypass Enable/Disable | Get/Set | 1, 0, 1 | UINT | 275 |
| 3 | Bypass Delay | Get/Set | 5, 0.5, 100 | REAL | 276/277 |
| 4 | Trip Delay | Get/Set | 0.1, 0.01, 100 | REAL | 278/279 |
| 5 | Trip Counter | Get | | UINT | 1150 |

Class 0x66, Instance 3 - Input 3

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------------|----------|---------------------------|-----------|---------------|
| 1 | Function | Get/Set | 0, 0, 19 | UINT | 284 |
| 2 | Bypass Enable/Disable | Get/Set | 1, 0, 1 | UINT | 285 |
| 3 | Bypass Delay | Get/Set | 5, 0.5, 100 | REAL | 286/287 |
| 4 | Trip Delay | Get/Set | 0.1, 0.01, 100 | REAL | 288/289 |
| 5 | Trip Counter | Get | | UINT | 1151 |

Class 0x66, Instance 4 - Input 4

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------------|----------|---------------------------|-----------|---------------|
| 1 | Function | Get/Set | 0, 0, 19 | UINT | 294 |
| 2 | Bypass Enable/Disable | Get/Set | 1, 0, 1 | UINT | 295 |
| 3 | Bypass Delay | Get/Set | 5, 0.5, 100 | REAL | 296/297 |
| 4 | Trip Delay | Get/Set | 0.1, 0.01, 100 | REAL | 298/299 |
| 5 | Trip Counter | Get | | UINT | 1152 |

Class 0x66, Instance 5 - Input 5

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------------|----------|---------------------------|-----------|---------------|
| 1 | Function | Get/Set | 0, 0, 19 | UINT | 304 |
| 2 | Bypass Enable/Disable | Get/Set | 1, 0, 1 | UINT | 305 |
| 3 | Bypass Delay | Get/Set | 5, 0.5, 100 | REAL | 306/307 |
| 4 | Trip Delay | Get/Set | 0.1, 0.01, 100 | REAL | 308/309 |
| 5 | Trip Counter | Get | | UINT | 1153 |

Class 0x66, Instance 6 - Input 6

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------------|----------|---------------------------|-----------|---------------|
| 1 | Function | Get/Set | 0, 0, 19 | UINT | 314 |
| 2 | Bypass Enable/Disable | Get/Set | 1, 0, 1 | UINT | 315 |
| 3 | Bypass Delay | Get/Set | 5, 0.5, 100 | REAL | 316/317 |
| 4 | Trip Delay | Get/Set | 0.1, 0.01, 100 | REAL | 318/319 |
| 5 | Trip Counter | Get | | UINT | 1154 |

Class 0x66, Instance 7 - Input 7

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------------|----------|---------------------------|-----------|---------------|
| 1 | Function | Get/Set | 0, 0, 19 | UINT | 324 |
| 2 | Bypass Enable/Disable | Get/Set | 1, 0, 1 | UINT | 325 |
| 3 | Bypass Delay | Get/Set | 5, 0.5, 100 | REAL | 326/327 |
| 4 | Trip Delay | Get/Set | 0.1, 0.01, 100 | REAL | 328/329 |
| 5 | Trip Counter | Get | | UINT | 1155 |

4.7 ANALOG I/O CLASS 0x67

Analog I/O Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Analog I/O Class (0x67), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

Analog I/O Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

Analog I/O Class (0x67), Instance (1) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 1 | Analog In Type | Get/Set | Defines the analog-input type: 0 = Disabled 1 = Generic (Trip1, Alarm1 enabled) 2 = Asd Sets Sampling Frequency 3 = Motor speed | 0, 0, 3 | UINT | 350 |
| 2 | High Trip | Get/Set | Sets high trip level for generic input type. (mA) | 16, 0.1, 20 | REAL | 351/352 |
| 3 | Low Trip | Get Set | Sets low trip level for generic input type. (mA) | 7, 0.1, 20 | REAL | 353/354 |
| 4 | Trip Delay | Get/Set | Applies to generic type. (s) | 5, 0.01, 100 | REAL | 355/356 |
| 5 | High Alarm | Get/Set | Sets high alarm level for generic input type. (mA) | 14, 0.1, 20 | REAL | 357/358 |
| 6 | Low Alarm | Get/Set | Sets low alarm level for generic input type. (mA) | 9, 0.1, 20 | REAL | 359/360 |
| 7 | Alarm Delay | Get/Set | Applies to generic type. (s) | 1, 0.01, 100 | REAL | 361/362 |
| 8 | ASD_4mA | Get/Set | Applies to type 2 input. Frequency corresponding to 4 mA input. (Hz) | 10, 0, 70 | REAL | 363/364 |
| 9 | ASD_20mA | Get/Set | Applies to type 2 input. Frequency corresponding to 20 mA input. (%FS) | 10, 0, 70 | REAL | 365/366 |
| 10 (0x0A) | Tach_4mA | Get/Set | Applies to type 3 input. % Speed corresponding to 4 mA input. (%FS) | 10, 0, 100 | REAL | 367/368 |
| 11 (0x0B) | Tach_20mA | Get/Set | Applies to type 3 input. % Speed corresponding to 20 mA input. (%FS) | 100, 0, 100 | REAL | 369/370 |

Analog I/O Class (0x67), Instance (1) Attributes (Continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 12 (0x0C) | Out Param | Get/Set | Specifies the analog output parameter: 0 = Phase Current 1 = Earth Leakage 2 = Thermal Capacity 3 = Max Stator RTD 4 = Max Bearing RTD 5 = Max Load RTD 6 = Max Ambient RTD 7 = Voltage 8 = Unbalance (I) 9 = Power Factor 10 = Real Power 11 = Reactive Power 12 = Apparent Power 13 = Zero (4 mA) 14 = Full Scale (20 mA) 15 = Speed 16 = Differential Current | 0, 0, 16 | UINT | 373/374 |
| 13 (0x0D) | Reading | Get | Analog Input Reading (mA) | 0, 0, 20 | REAL | 884/885 |
| 14 (0x0E) | High Trips | Get | Input-High Trip Count | | UINT | 1140 |
| 15 (0x0F) | Low Trips | Get | Input-Low Trip Count | | UINT | 1141 |

4.8 RTD MODULE CLASS 0x68
RTD Module Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

Class 0x68, Instance 0, Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|--------------------|----------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 1 | Revision Number | Get | Revision number of this class | 1 | UINT | |
| 2 | Max Instance | Get | Maximum number of RTD modules | 3 | UINT | |
| 100 (0x64) | Modules Used | Get/Set | Specifies the number of RTD modules used | 0, 0, 3 | UINT | 390 |
| 101 (0x65) | Sensor Trip Action | Get/Set | Specifies trip action to take on a sensor error. 0 = Disable Trips 1 = Trip1 ⁽¹⁾ 2 = Trip2 3 = Trip3 4 = Trip1 & Trip2 5 = Trip1 & Trip3 6 = Trip1 & Trip2 & Trip3 7 = Trip2 & Trip3 ⁽¹⁾ Initiates a STOP when a starter function is enabled. | 0, 0, 7 | UINT | 388 |

Class 0x68, Instance 0, Attributes (Continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|---------------------------|----------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 102 (0x66) | Sensor Alarm Action | Get/Set | Specifies alarm action to take on a sensor error. 0 = Disable Alarms 1 = Alarm1 2 = Alarm2 3 = Alarm3 4 = Alarm1 & Alarm2 5 = Alarm1 & Alarm3 6 = Alarm1 & Alarm2 & Alarm3 7 = Alarm2 & Alarm3 | 1, 0, 7 | UINT | 379 |
| 103 (0x67) | Module Error Trip Action | Get/Set | Specifies trip action to take on a module error. Action list is the same as Attribute 9. | 0, 0, 7 | UINT | 389 |
| 104 (0x68) | Module Error Alarm Action | Get/Set | Specifies alarm action to take on a module error. Action list is the same as Attribute A. | 1, 0, 7 | UINT | 380 |
| 105 (0x69) | Module1 Comm Trip Count | Get | Number of module1 communication-error trips. | | UINT | 1180 |
| 106 (0x6A) | Module2 Comm Trip Count | Get | Number of module2 communication-error trips. | | UINT | 1181 |
| 107 (0x6B) | Module3 Comm Trip Count | Get | Number of module3 communication-error trips. | | UINT | 1182 |
| 108 (0x6C) | Sensor Trip Count | Get | Number of RTD Sensor Trips | | UINT | 1183 |
| 109 (0x6D) | HMC Enable | Get/Set | Hot Motor Compensation control. 0 = Enable, 1 = Disable | | UINT | 550 |
| 110 (0x6E) | HMC Max Bias | Get/Set | Stator temperature (°C) where compensation ends at 100% I _{pt} . | 150, 40, 200 | REAL | 551/552 |
| 111 (0x6F) | HMC Min Bias | Get/Set | Stator temperature (°C) where compensation begins at 0% I _{pt} . | 40, 40, 200 | REAL | 553/554 |
| 112 (0x70) | Max Stator Temp | Get | Max Stator Temperature (°C) | | REAL | 950/951 |
| 113 (0x71) | Max Bearing Temp | Get | Max Bearing Temperature (°C) | | REAL | 952/953 |
| 114 (0x72) | Max Load Temp | Get | Max Load Temperature (°C) | | REAL | 954/955 |
| 115 (0x73) | Max Amb Temp | Get | Max Ambient Temperature (°C) | | REAL | 956/957 |
| 116 (0x74) | Min Stator Temp | Get | Min Stator Temperature (°C) | | REAL | 958/959 |
| 117 (0x75) | Min Bearing Temp | Get | Min Bearing Temperature (°C) | | REAL | 960/961 |
| 118 (0x76) | Min Load Temp | Get | Min Load Temperature (°C) | | REAL | 962/963 |
| 119 (0x77) | Min Ambient Temp | Get | Min Ambient Temperature (°C) | | REAL | 964/965 |
| 120 (0x78) | Temperature Trip Action | Get/Set | Specifies trip action to take on a sensor error. 0 = Disable Trips 1 = Trip1 ⁽¹⁾ 2 = Trip2 3 = Trip3 4 = Trip1 & Trip2 5 = Trip1 & Trip3 6 = Trip1 & Trip2 & Trip3 7 = Trip2 & Trip3 ⁽¹⁾ Initiates a STOP when a starter function is enabled. | 1, 0, 7 | UINT | 548 |

Class 0x68, Instance 0, Attributes (Continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|--------------------------|----------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 121 (0x79) | Temperature Alarm Action | Get/Set | Specifies alarm action to take on a sensor error. 0 = Disable Alarms 1 = Alarm1 2 = Alarm2 3 = Alarm3 4 = Alarm1 & Alarm2 5 = Alarm1 & Alarm3 6 = Alarm1 & Alarm2 & Alarm3 7 = Alarm2 & Alarm3 | 1, 0, 7 | UINT | 549 |

RTD Module Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

Object Instance Attributes 1 to 8 define the RTD type. Selecting an RTD will enable trip and alarm set points. The trip action is fixed as Trip1 and the alarm action is fixed as Alarm1.

- 0 = RTD Disabled
- 1 = Platinum 100 ohm
- 2 = Nickel 100 ohm
- 3 = Nickel 120 ohm
- 4 = Copper 10 ohm

Object Instance Attributes 0x09 to 0x10 define the RTD function.

- 0 = Stator
- 1 = Bearing
- 2 = Load
- 3 = Ambient

Object Instance Attributes 0x11 to 0x20 define the trip and alarm settings in degrees C. The trip action is fixed as Trip1 and the alarm action is fixed as Alarm1.

Object Instance Attributes 0x21 to 0x28 define an 18-character name.

Object Instance Attributes 0x29 to 0x30 are temperature readings.

Object Instance Attributes 0x31 to 0x38 are the trip counters for each of the RTD's.

Class 0x68, Instance 1

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------|----------|---------------------------|-----------|---------------|
| 1 | RTD #1 Type | Get/Set | 0, 0, 4 | UINT | 391 |
| 2 | RTD #2 Type | Get/Set | 0, 0, 4 | UINT | 392 |
| 3 | RTD #3 Type | Get/Set | 0, 0, 4 | UINT | 393 |
| 4 | RTD #4 Type | Get/Set | 0, 0, 4 | UINT | 394 |
| 5 | RTD #5 Type | Get/Set | 0, 0, 4 | UINT | 395 |
| 6 | RTD #6 Type | Get/Set | 0, 0, 4 | UINT | 396 |
| 7 | RTD #7 Type | Get/Set | 0, 0, 4 | UINT | 397 |
| 8 | RTD #8 Type | Get/Set | 0, 0, 4 | UINT | 398 |
| 9 | RTD #1 Function | Get/Set | 0, 0, 3 | UINT | 415 |
| 10 (0x0A) | RTD #2 Function | Get/Set | 0, 0, 3 | UINT | 416 |
| 11 (0x0B) | RTD #3 Function | Get/Set | 0, 0, 3 | UINT | 417 |
| 12 (0x0C) | RTD #4 Function | Get/Set | 0, 0, 3 | UINT | 418 |
| 13 (0x0D) | RTD #5 Function | Get/Set | 0, 0, 3 | UINT | 419 |
| 14 (0x0E) | RTD #6 Function | Get/Set | 0, 0, 3 | UINT | 420 |
| 15 (0x0F) | RTD #7 Function | Get/Set | 0, 0, 3 | UINT | 421 |

Class 0x68, Instance 1 (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|--------------------|----------|---------------------------|--------------|---------------|
| 16 (0x10) | RTD #8 Function | Get/Set | 0, 0, 3 | UINT | 422 |
| 17 (0x11) | RTD #1 Trip Level | Get/Set | 130, 40, 200 | REAL | 446/447 |
| 18 (0x12) | RTD #1 Alarm Level | Get/Set | 110, 40, 200 | REAL | 448/449 |
| 19 (0x13) | RTD #2 Trip Level | Get/Set | 130, 40, 200 | REAL | 450/451 |
| 20 (0x14) | RTD #2 Alarm Level | Get/Set | 110, 40, 200 | REAL | 452/453 |
| 21 (0x15) | RTD #3 Trip Level | Get/Set | 130, 40, 200 | REAL | 454/455 |
| 22 (0x16) | RTD #3 Alarm Level | Get/Set | 110, 40, 200 | REAL | 456/457 |
| 23 (0x17) | RTD #4 Trip Level | Get/Set | 130, 40, 200 | REAL | 458/459 |
| 24 (0x18) | RTD #4 Alarm Level | Get/Set | 110, 40, 200 | REAL | 460/461 |
| 25 (0x19) | RTD #5 Trip Level | Get/Set | 130, 40, 200 | REAL | 462/463 |
| 26 (0x1A) | RTD #5 Alarm Level | Get/Set | 110, 40, 200 | REAL | 464/465 |
| 27 (0x1B) | RTD #6 Trip Level | Get/Set | 130, 40, 200 | REAL | 466/467 |
| 28 (0x1C) | RTD #6 Alarm Level | Get/Set | 110, 40, 200 | REAL | 468/469 |
| 29 (0x1D) | RTD #7 Trip Level | Get/Set | 130, 40, 200 | REAL | 470/471 |
| 30 (0x1E) | RTD #7 Alarm Level | Get/Set | 110, 40, 200 | REAL | 472/473 |
| 31 (0x1F) | RTD #8 Trip Level | Get/Set | 130, 40, 200 | REAL | 474/475 |
| 32 (0x20) | RTD #8 Alarm Level | Get/Set | 110, 40, 200 | REAL | 476/477 |
| 33 (0x21) | RTD #1 Name | Get/Set | RTD M1 #1 | SHORT_STRING | 610..619 |
| 34 (0x22) | RTD #2 Name | Get/Set | RTD M1 #2 | SHORT_STRING | 620..629 |
| 35 (0x23) | RTD #3 Name | Get/Set | RTD M1 #3 | SHORT_STRING | 630..639 |
| 36 (0x24) | RTD #4Name | Get/Set | RTD M1 #4 | SHORT_STRING | 640..649 |
| 37 (0x25) | RTD #5 Name | Get/Set | RTD M1 #5 | SHORT_STRING | 650..659 |
| 38 (0x26) | RTD #6 Name | Get/Set | RTD M1 #6 | SHORT_STRING | 660..669 |
| 39 (0x27) | RTD #7 Name | Get/Set | RTD M1 #7 | SHORT_STRING | 670..679 |
| 40 (0x28) | RTD #8 Name | Get/Set | RTD M1 #8 | SHORT_STRING | 680..689 |
| 41 (0x29) | RTD #1 Temp RDG | Get | | REAL | 902/903 |
| 42 (0x2A) | RTD #2 Temp RDG | Get | | REAL | 904/905 |

Class 0x68, Instance 1 (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|------------------|----------|---------------------------|-----------|---------------|
| 43 (0x2B) | RTD #3 Temp RDG | Get | | REAL | 906/907 |
| 44 (0x2C) | RTD #4 Temp RDG | Get | | REAL | 908/909 |
| 45 (0x2D) | RTD #5 Temp RDG | Get | | REAL | 910/911 |
| 46 (0x2E) | RTD #6 Temp RDG | Get | | REAL | 912/913 |
| 47 (0x2F) | RTD #7 Temp RDG | Get | | REAL | 914/915 |
| 48 (0x30) | RTD #8 Temp RDG | Get | | REAL | 916/917 |
| 49 (0x31) | RTD #1 Trip Cntr | Get | | UINT | 1156 |
| 50 (0x32) | RTD #2 Trip Cntr | Get | | UINT | 1157 |
| 51 (0x33) | RTD #3 Trip Cntr | Get | | UINT | 1158 |
| 52 (0x34) | RTD #4 Trip Cntr | Get | | UINT | 1159 |
| 53 (0x35) | RTD #5 Trip Cntr | Get | | UINT | 1160 |
| 54 (0x36) | RTD #6 Trip Cntr | Get | | UINT | 1161 |
| 55 (0x37) | RTD #7 Trip Cntr | Get | | UINT | 1162 |
| 56 (0x38) | RTD #8 Trip Cntr | Get | | UINT | 1163 |

Class 0x68, Instance 2

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|--------------------|----------|---------------------------|--------------|---------------|
| 1 | RTD #1 Type | Get/Set | 0, 0, 4 | UINT | 399 |
| 2 | RTD #2 Type | Get/Set | 0, 0, 4 | UINT | 400 |
| 3 | RTD #3 Type | Get/Set | 0, 0, 4 | UINT | 401 |
| 4 | RTD #4 Type | Get/Set | 0, 0, 4 | UINT | 402 |
| 5 | RTD #5 Type | Get/Set | 0, 0, 4 | UINT | 403 |
| 6 | RTD #6 Type | Get/Set | 0, 0, 4 | UINT | 404 |
| 7 | RTD #7 Type | Get/Set | 0, 0, 4 | UINT | 405 |
| 8 | RTD #8 Type | Get/Set | 0, 0, 4 | UINT | 406 |
| 9 | RTD #1 Function | Get/Set | 0, 0, 3 | UINT | 423 |
| 10 (0x0A) | RTD #2 Function | Get/Set | 0, 0, 3 | UINT | 424 |
| 11 (0x0B) | RTD #3 Function | Get/Set | 0, 0, 3 | UINT | 425 |
| 12 (0x0C) | RTD #4 Function | Get/Set | 0, 0, 3 | UINT | 426 |
| 13 (0x0D) | RTD #5 Function | Get/Set | 0, 0, 3 | UINT | 427 |
| 14 (0x0E) | RTD #6 Function | Get/Set | 0, 0, 3 | UINT | 428 |
| 15 (0x0F) | RTD #7 Function | Get/Set | 0, 0, 3 | UINT | 429 |
| 16 (0x10) | RTD #8 Function | Get/Set | 0, 0, 3 | UINT | 430 |
| 17 (0x11) | RTD #1 Trip Level | Get/Set | 130, 40, 200 | REAL | 478 |
| 18 (0x12) | RTD #1 Alarm Level | Get/Set | 110, 40, 200 | REAL | 480 |
| 19 (0x13) | RTD #2 Trip Level | Get/Set | 130, 40, 200 | REAL | 482/483 |
| 20 (0x14) | RTD #2 Alarm Level | Get/Set | 110, 40, 200 | REAL | 484/485 |
| 21 (0x15) | RTD #3 Trip Level | Get/Set | 130, 40, 200 | REAL | 486/487 |
| 22 (0x16) | RTD #3 Alarm Level | Get/Set | 110, 40, 200 | REAL | 488/489 |
| 23 (0x17) | RTD #4 Trip Level | Get/Set | 130, 40, 200 | REAL | 490/491 |
| 24 (0x18) | RTD #4 Alarm Level | Get/Set | 110, 40, 200 | REAL | 492/493 |
| 25 (0x19) | RTD #5 Trip Level | Get/Set | 130, 40, 200 | REAL | 494/495 |
| 26 (0x1A) | RTD #5 Alarm Level | Get/Set | 110, 40, 200 | REAL | 496/497 |
| 27 (0x1B) | RTD #6 Trip Level | Get/Set | 130, 40, 200 | REAL | 498/499 |
| 28 (0x1C) | RTD #6 Alarm Level | Get/Set | 110, 40, 200 | REAL | 500/501 |
| 29 (0x1D) | RTD #7 Trip Level | Get/Set | 130, 40, 200 | REAL | 502/503 |
| 30 (0x1E) | RTD #7 Alarm Level | Get/Set | 110, 40, 200 | REAL | 504/505 |
| 31 (0x1F) | RTD #8 Trip Level | Get/Set | 130, 40, 200 | REAL | 506/507 |
| 32 (0x20) | RTD #8 Alarm Level | Get/Set | 110, 40, 200 | REAL | 508/509 |
| 33 (0x21) | RTD #1 Name | Get/Set | RTD M2 #1 | SHORT_STRING | 690..699 |
| 34 (0x22) | RTD #2 Name | Get/Set | RTD M2 #2 | SHORT_STRING | 700..709 |

Class 0x68, Instance 2 (Continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|------------------|----------|---------------------------|--------------|---------------|
| 35 (0x23) | RTD #3 Name | Get/Set | RTD M2 #3 | SHORT_STRING | 710..719 |
| 36 (0x24) | RTD #4Name | Get/Set | RTD M2 #4 | SHORT_STRING | 720..729 |
| 37 (0x25) | RTD #5 Name | Get/Set | RTD M2 #5 | SHORT_STRING | 730..739 |
| 38 (0x26) | RTD #6 Name | Get/Set | RTD M2 #6 | SHORT_STRING | 740..749 |
| 39 (0x27) | RTD #7 Name | Get/Set | RTD M2 #7 | SHORT_STRING | 750..759 |
| 40 (0x28) | RTD #8 Name | Get/Set | RTD M2 #8 | SHORT_STRING | 760..769 |
| 41 (0x29) | RTD #1 Temp RDG | Get | | REAL | 918/919 |
| 42 (0x2A) | RTD #2 Temp RDG | Get | | REAL | 920/921 |
| 43 (0x2B) | RTD #3 Temp RDG | Get | | REAL | 922/923 |
| 44 (0x2C) | RTD #4 Temp RDG | Get | | REAL | 924/925 |
| 45 (0x2D) | RTD #5 Temp RDG | Get | | REAL | 926/927 |
| 46 (0x2E) | RTD #6 Temp RDG | Get | | REAL | 928/929 |
| 47 (0x2F) | RTD #7 Temp RDG | Get | | REAL | 930/931 |
| 48 (0x30) | RTD #8 Temp RDG | Get | | REAL | 932/933 |
| 49 (0x31) | RTD #1 Trip Cntr | Get | | UINT | 1164 |
| 50 (0x32) | RTD #2 Trip Cntr | Get | | UINT | 1165 |
| 51 (0x33) | RTD #3 Trip Cntr | Get | | UINT | 1166 |
| 52 (0x34) | RTD #4 Trip Cntr | Get | | UINT | 1167 |
| 53 (0x35) | RTD #5 Trip Cntr | Get | | UINT | 1168 |
| 54 (0x36) | RTD #6 Trip Cntr | Get | | UINT | 1169 |
| 55 (0x37) | RTD #7 Trip Cntr | Get | | UINT | 1170 |
| 56 (0x38) | RTD #8 Trip Cntr | Get | | UINT | 1171 |

Class 0x68, Instance 3

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|--------------------|----------|---------------------------|-----------|---------------|
| 1 | RTD #1 Type | Get/Set | 0, 0, 4 | UINT | 407 |
| 2 | RTD #2 Type | Get/Set | 0, 0, 4 | UINT | 408 |
| 3 | RTD #3 Type | Get/Set | 0, 0, 4 | UINT | 409 |
| 4 | RTD #4 Type | Get/Set | 0, 0, 4 | UINT | 410 |
| 5 | RTD #5 Type | Get/Set | 0, 0, 4 | UINT | 411 |
| 6 | RTD #6 Type | Get/Set | 0, 0, 4 | UINT | 412 |
| 7 | RTD #7 Type | Get/Set | 0, 0, 4 | UINT | 413 |
| 8 | RTD #8 Type | Get/Set | 0, 0, 4 | UINT | 414 |
| 9 | RTD #1 Function | Get/Set | 0, 0, 3 | UINT | 431 |
| 10 (0x0A) | RTD #2 Function | Get/Set | 0, 0, 3 | UINT | 432 |
| 11 (0x0B) | RTD #3 Function | Get/Set | 0, 0, 3 | UINT | 433 |
| 12 (0x0C) | RTD #4 Function | Get/Set | 0, 0, 3 | UINT | 434 |
| 13 (0x0D) | RTD #5 Function | Get/Set | 0, 0, 3 | UINT | 435 |
| 14 (0x0E) | RTD #6 Function | Get/Set | 0, 0, 3 | UINT | 436 |
| 15 (0x0F) | RTD #7 Function | Get/Set | 0, 0, 3 | UINT | 437 |
| 16 (0x10) | RTD #8 Function | Get/Set | 0, 0, 3 | UINT | 438 |
| 17 (0x11) | RTD #1 Trip Level | Get/Set | 130, 40, 200 | REAL | 510/511 |
| 18 (0x12) | RTD #1 Alarm Level | Get/Set | 110, 40, 200 | REAL | 512/513 |
| 19 (0x13) | RTD #2 Trip Level | Get/Set | 130, 40, 200 | REAL | 514/515 |
| 20 (0x14) | RTD #2 Alarm Level | Get/Set | 110, 40, 200 | REAL | 516/517 |
| 21 (0x15) | RTD #3 Trip Level | Get/Set | 130, 40, 200 | REAL | 518/519 |
| 22 (0x16) | RTD #3 Alarm Level | Get/Set | 110, 40, 200 | REAL | 520/521 |
| 23 (0x17) | RTD #4 Trip Level | Get/Set | 130, 40, 200 | REAL | 522/523 |

Class 0x68, Instance 3 (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|--------------------|----------|---------------------------|--------------|---------------|
| 24 (0x18) | RTD #4 Alarm Level | Get/Set | 110, 40, 200 | REAL | 524/525 |
| 25 (0x19) | RTD #5 Trip Level | Get/Set | 130, 40, 200 | REAL | 526/527 |
| 26 (0x1A) | RTD #5 Alarm Level | Get/Set | 110, 40, 200 | REAL | 528/529 |
| 27 (0x1B) | RTD #6 Trip Level | Get/Set | 130, 40, 200 | REAL | 530/531 |
| 28 (0x1C) | RTD #6 Alarm Level | Get/Set | 110, 40, 200 | REAL | 532/533 |
| 29 (0x1D) | RTD #7 Trip Level | Get/Set | 130, 40, 200 | REAL | 534/535 |
| 30 (0x1E) | RTD #7 Alarm Level | Get/Set | 110, 40, 200 | REAL | 536/537 |
| 31 (0x1F) | RTD #8 Trip Level | Get/Set | 130, 40, 200 | REAL | 538/539 |
| 32 (0x20) | RTD #8 Alarm Level | Get/Set | 110, 40, 200 | REAL | 540/541 |
| 33 (0x21) | RTD #1 Name | Get/Set | RTD M3 #1 | SHORT_STRING | 770..779 |
| 34 (0x22) | RTD #2 Name | Get/Set | RTD M3 #2 | SHORT_STRING | 780..789 |
| 35 (0x23) | RTD #3 Name | Get/Set | RTD M3 #3 | SHORT_STRING | 790..799 |
| 36 (0x24) | RTD #4Name | Get/Set | RTD M3 #4 | SHORT_STRING | 800..809 |
| 37 (0x25) | RTD #5 Name | Get/Set | RTD M3 #5 | SHORT_STRING | 810..819 |
| 38 (0x26) | RTD #6 Name | Get/Set | RTD M3 #6 | SHORT_STRING | 820..829 |
| 39 (0x27) | RTD #7 Name | Get/Set | RTD M3 #7 | SHORT_STRING | 830..839 |
| 40 (0x28) | RTD #8 Name | Get/Set | RTD M3 #8 | SHORT_STRING | 840..849 |
| 41 (0x29) | RTD #1 Temp RDG | Get | | REAL | 934..935 |
| 42 (0x2A) | RTD #2 Temp RDG | Get | | REAL | 936..937 |
| 43 (0x2B) | RTD #3 Temp RDG | Get | | REAL | 938..939 |
| 44 (0x2C) | RTD #4 Temp RDG | Get | | REAL | 940..941 |
| 45 (0x2D) | RTD #5 Temp RDG | Get | | REAL | 942..943 |
| 46 (0x2E) | RTD #6 Temp RDG | Get | | REAL | 944..945 |
| 47 (0x2F) | RTD #7 Temp RDG | Get | | REAL | 946/947 |
| 48 (0x30) | RTD #8 Temp RDG | Get | | REAL | 948/949 |
| 49 (0x31) | RTD #1 Trip Cntr | Get | | UINT | 1172 |
| 50 (0x32) | RTD #2 Trip Cntr | Get | | UINT | 1173 |
| 51 (0x33) | RTD #3 Trip Cntr | Get | | UINT | 1174 |
| 52 (0x34) | RTD #4 Trip Cntr | Get | | UINT | 1175 |
| 53 (0x35) | RTD #5 Trip Cntr | Get | | UINT | 1176 |
| 54 (0x36) | RTD #6 Trip Cntr | Get | | UINT | 1177 |
| 55 (0x37) | RTD #7 Trip Cntr | Get | | UINT | 1178 |
| 56 (0x38) | RTD #8 Trip Cntr | Get | | UINT | 1179 |

4.9 RTC CLASS 0x69
RTC Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

RTC Class (0x69), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

RTC Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

RTC Class (0x69), Instance (1) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------|------------------------|--------------------------------------------------------|---------------------------|--------------|---------------|
| 1 | IRIG Hrs Offset | Get/Set | RTC Hrs = IRIG Hrs + IRIG Hr Offset | 0, 0, 30 | REAL | 568/569 |
| 2 | IRIG Min Offset | Get/Set | RTC Min = IRIG Min + IRIG Min Offset | 0, 0, 23 | REAL | 570/571 |
| 3 | RTC Date | Get | Number of Days Since 1972-01-01 | | DATE | 574/575 |
| 4 | RTC Time | Get | Number of Milliseconds Since 00:00:00:00.000 | | TIME OF DAY | 576/577 |
| 5 | RTC Set | Get/Set ⁽¹⁾ | String Used to Set the Date and Time YY/MM/DD-HH:MM:SS | | SHORT_STRING | 580/589 |

⁽¹⁾ Time value is not activated until a SET RTC command is issued using Class 0x29, Instance 1, Attribute 0x64.

4.10 USER REGISTER CLASS 0x6A

This object defines the communication registers that generate the data for Assembly Class 4, Instance 0x64, Attribute 3. Register values are defined in Appendix E of the Main Product Manual. Each register in Appendix E defines a 16-bit value.

User Register Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

User Register Class (0x6A), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

User Register Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

User Register Class (0x6A), Instance (1) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------|---------------------------|-----------|---------------|
| 1 | Register 1 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1400 |
| 2 | Register 2 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1401 |
| 3 | Register 3 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1402 |
| 4 | Register 4 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1403 |
| 5 | Register 5 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1404 |
| 6 | Register 6 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1405 |
| 7 | Register 7 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1406 |
| 8 | Register 8 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1407 |
| 9 | Register 9 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1408 |
| 10 | Register 10 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1409 |
| 11 | Register 11 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1410 |

User Register Class (0x6A), Instance (1) Attributes (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|----------------|----------|---------------------|---------------------------|-----------|---------------|
| 12 | Register 12 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1411 |
| 13 | Register 13 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1412 |
| 14 | Register 14 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1413 |
| 15 | Register 15 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1414 |
| 16 | Register 16 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1415 |
| 32 | Register 32 | Get/Set | User Register Value | 0, 0, 1246 | UINT | 1431 |

4.11 DATA LOGGING CLASS 0x6B

This object is used to access one of 64 data-logging records. The Record Selector value defines the record that is displayed. Record Head indicates the record number for the latest record.

Data Logging Object Class Services

Get_Attribute_Single: Returns contents of specified attribute.

Data Logging Class (0x6B), Instance (0) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE |
|------------------|----------------|----------|------------------------------|---------------------------|-----------|
| 1 | Revision | Get | Revision of this object. | 1 | UINT |
| 2 | Max Instance | Get | Maximum number of instances. | 1 | UINT |

Data Logging Object Instance Services

Get_Attribute_Single: Returns contents of specified attribute.

Set_Attribute_Single: Modifies specified attribute.

Data Logging Class (0x6B), Instance (1) Attributes

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|-----------------|----------|------------------------------------------------------------------------------------------------------|---------------------------|-----------|---------------|
| 1 | Record Count | Get | Number of captured records since the last time the event records were cleared. | 0, 0, 65535 | UINT | 973 |
| 2 | Record Head | Get | Points to next record. Latest record at Record Head minus 1. | 0, 0, 63 | UINT | 974 |
| 3 | Record Selector | Get/Set | Selects the record for which the data is displayed in this instance. | 0, 0, 63 | UINT | 975 |
| 4 | Record Date | Get | The date when the record was captured. | 0, 0, 65535 | DATE | 976/977 |
| 5 | Record Time | Get | Time-of-Day the record was captured. | 0, 0, 86399999 | TOD | 978/979 |
| 6 | Record Type | Get | Specifies the trigger source: 0 = Record Empty 1 = Triggered by start 2 = Triggered by trip | 0, 0, 2 | UINT | 980 |
| 7 | Trip Code | Get | See Main Product Manual Appendix F T27 for a list of trip codes. 255 = No Trip or Alarm | 0, 0, 255 | UINT | 981 |
| 8 | IA | Get | Phase A Current (A) ⁽¹⁾ | | Real | 982 |
| 9 | IB | Get | Phase B Current (A) ⁽¹⁾ | | Real | 984 |

Data Logging Class (0x6B), Instance (1) Attributes (continued)

| ATTRIBUTE NUMBER | ATTRIBUTE NAME | SERVICES | DESCRIPTION | DEFAULT, MINIMUM, MAXIMUM | DATA TYPE | COMM REGISTER |
|------------------|------------------------|----------|---------------------------------------------------------------------|---------------------------|-----------|---------------|
| 10 (0x0A) | IC | Get | Phase C Current (A) ⁽¹⁾ | | Real | 986 |
| 11 (0x0B) | 3IA | Get | Ground-Fault Current (A) ⁽¹⁾ | | Real | 988 |
| 12 (0x0C) | Vab | Get | Line-to-Line Voltage (kV) ⁽¹⁾ | | Real | 990 |
| 13 (0x0D) | Vbc | Get | Line-to-Line Voltage (kV) ⁽¹⁾ | | Real | 992 |
| 14 (0x0E) | Vca | Get | Line-to-Line Voltage (kV) ⁽¹⁾ | | Real | 994 |
| 15 (0x0F) | Frequency | Get | Frequency in Hz | | Real | 1053/1054 |
| 16 (0x10) | S | Get | Apparent Power (kVA) | | Real | 1055/1056 |
| 17 (0x11) | P | Get | Real Power (kW) | | Real | 1057/1058 |
| 18 (0x12) | Q | Get | Reactive Power (kVAR) | | Real | 1059/1060 |
| 19 (0x13) | PF | Get | Power Factor (-1, +1) | | Real | 1061/1062 |
| 20 (0x14) | Ain | Get | Analog Input (mA) | | Real | 996/997 |
| 21 (0x15) | Unbalance I | Get | Current Unbalance (pu) ⁽¹⁾ | | Real | 998/999 |
| 22 (0x16) | Unbalance V | Get | Voltage Unbalance (pu) ⁽¹⁾ | | Real | 1000/1001 |
| 23 (0x17) | Start Time | Get | Start time in seconds. Only valid for start-type records. | | UINT | 1002 |
| 24 (0x18) | I ² t Used | Get | For start records this is the I ² t used during a start. | | REAL | 1003/1004 |
| 32 (0x20) | M1 RTD1 | Get | RTD Temperature Reading (°C) | | REAL | 1005/1006 |
| 33 (0x21) | M1 RTD2 | Get | RTD Temperature Reading (°C) | | REAL | 1007/1008 |
| 34 (0x22) | M1 RTD3 | Get | RTD Temperature Reading (°C) | | REAL | 1009/1010 |
| 35 (0x23) | M1 RTD4 | Get | RTD Temperature Reading (°C) | | REAL | 1011/1012 |
| 36 (0x24) | M1 RTD5 | Get | RTD Temperature Reading (°C) | | REAL | 1013/1014 |
| 37 (0x25) | M1 RTD6 | Get | RTD Temperature Reading (°C) | | REAL | 1015/1016 |
| 38 (0x26) | M1 RTD7 | Get | RTD Temperature Reading (°C) | | REAL | 1017/1018 |
| 39 (0x27) | M1 RTD8 | Get | RTD Temperature Reading (°C) | | REAL | 1019/1020 |
| 40 (0x28) | M2 RTD1 | Get | RTD Temperature Reading (°C) | | REAL | 1021/1022 |
| 41 (0x29) | M2 RTD2 | Get | RTD Temperature Reading (°C) | | REAL | 1023/1024 |
| 42 (0x2A) | M2 RTD3 | Get | RTD Temperature Reading (°C) | | REAL | 1025/1026 |
| 43 (0x2B) | M2 RTD4 | Get | RTD Temperature Reading (°C) | | REAL | 1027/1028 |
| 44 (0x2C) | M2 RTD5 | Get | RTD Temperature Reading (°C) | | REAL | 1029/1030 |
| 45 (0x2D) | M2 RTD6 | Get | RTD Temperature Reading (°C) | | REAL | 1031/1032 |
| 46 (0x2E) | M2 RTD7 | Get | RTD Temperature Reading (°C) | | REAL | 1033/1034 |
| 47 (0x2F) | M2 RTD8 | Get | RTD Temperature Reading (°C) | | REAL | 1035/1036 |
| 48 (0x30) | M3 RTD1 ⁽²⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1037/1038 |
| 49 (0x31) | M3 RTD2 ⁽³⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1039/1040 |
| 50 (0x32) | M3 RTD3 ⁽⁴⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1041/1042 |
| 51 (0x33) | M3 RTD4 ⁽⁵⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1043/1044 |
| 52 (0x34) | M3 RTD5 ⁽⁵⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1045/1046 |
| 53 (0x35) | M3 RTD6 ⁽⁵⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1047/1048 |
| 54 (0x36) | M3 RTD7 ⁽⁵⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1049/1050 |
| 55 (0x37) | M3 RTD8 ⁽⁵⁾ | Get | RTD Temperature Reading (°C) | | REAL | 1051/1052 |

⁽¹⁾ For start records, current and unbalance are maximum values recorded during the start. Voltages are the minimum values recorded during the start.

⁽²⁾ Phase A differential current for firmware > 2.30

⁽³⁾ Phase B differential current for firmware > 2.30

⁽⁴⁾ Phase C differential current for firmware > 2.30

⁽⁵⁾ Ignore this value for firmware > 2.30

5. HARDWARE SPECIFICATIONS

Interface10Base-T, 100Base-T,
Cat. 3, 4, 5, UTP, STP
Protocol.....EtherNet/IP or Modbus TCP
Baud Rate.....10/100 Mbps
Number of Slaves Connected.....Up to 254 units
Number of Connections/SlaveUp to five
Bus length.....100 m (328') per segment

APPENDIX A**MPS MODBUS TCP & ETHERNET/IP INTERFACE REVISION HISTORY**

| MANUAL RELEASE DATE | MANUAL REVISION |
|----------------------------|------------------------|
| June 11, 2015 | 1-B-061115 |
| March 31, 2014 | 1-A-033114 |

MANUAL REVISION HISTORY**REVISION 1-B-061115**

Added RTD Module Set Point Class, Instance 0, Attributes 120 and 121.

REVISION 1-A-033114

Updated Set Point Class, Instance 0 default, minimum and maximum.

Added Underpower and Reversepower instances.